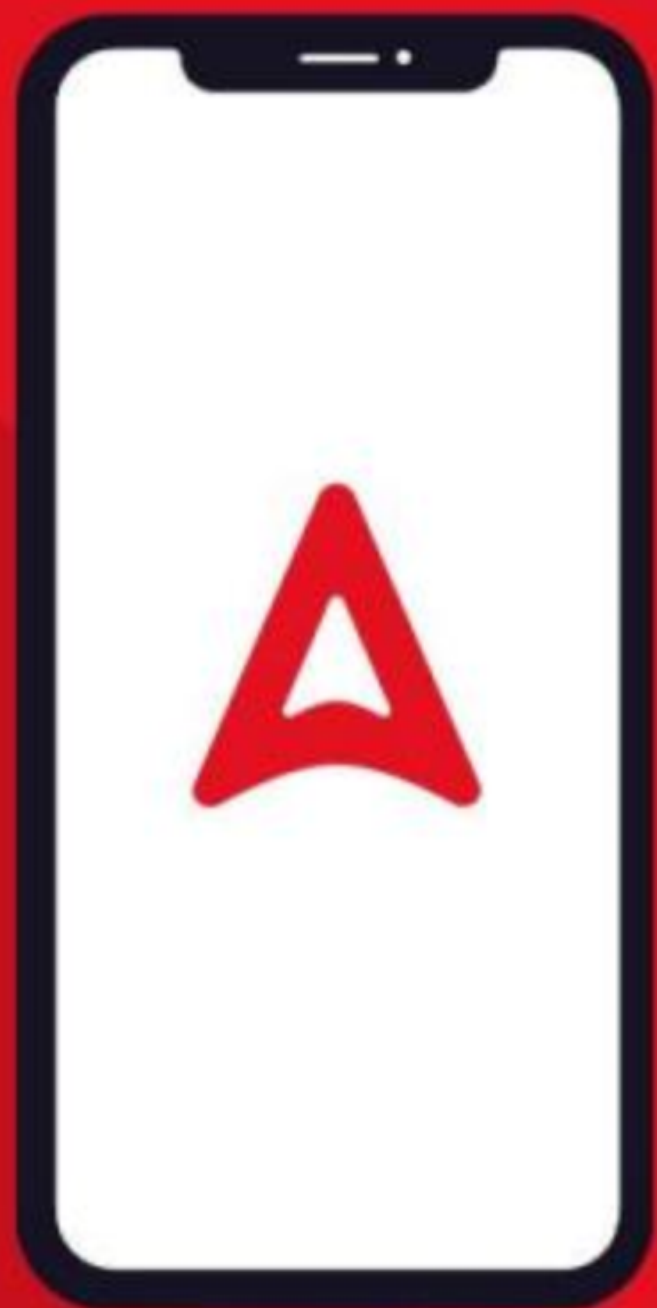


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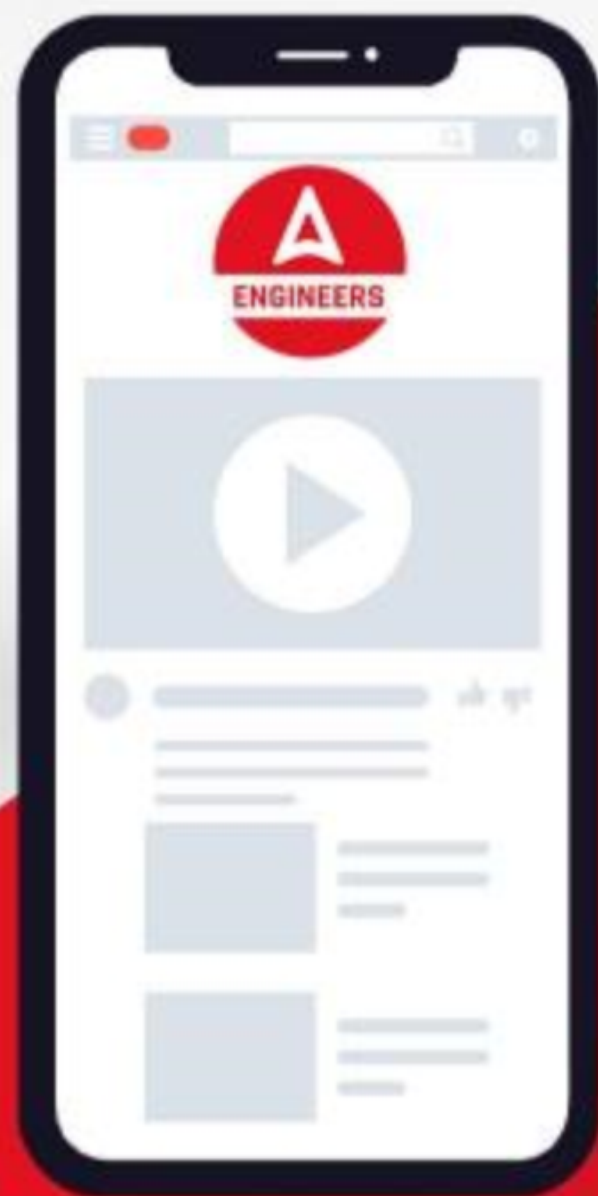


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Control system

unit step response order-2 system

$$\frac{C(s)}{R(s)} = \frac{\omega_n^2}{s^2 + 2\zeta\omega_n s + \omega_n^2}$$

$$R(s) \rightarrow \frac{1}{s} \quad r(t) \rightarrow u(t)$$

$$c(t) = 1 - \frac{e^{-\zeta\omega_n t}}{\sqrt{1-\zeta^2}} \sin(\omega_d t + \theta)$$

$$\theta = \tan^{-1} \frac{\sqrt{1-\zeta^2}}{\zeta}$$

$$\cos \theta = \zeta$$

$$\omega_d = \omega_n \sqrt{1-\zeta^2}$$

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$$c(t) = 1 - \frac{e^{-\zeta \omega_n t}}{\sqrt{1-\zeta^2}} \sin(\omega_d t + \theta)$$

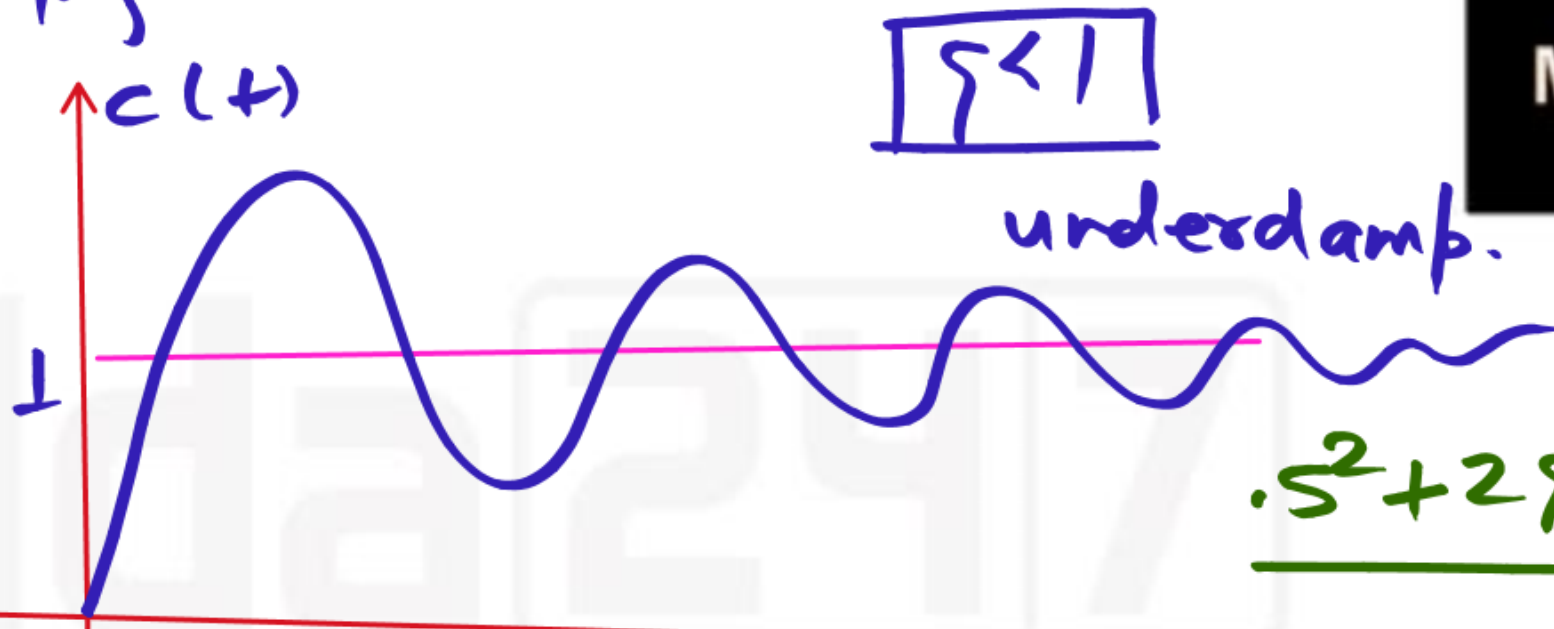
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$\zeta \omega_n$ → damping factor.

$\zeta = \frac{\zeta \omega_n}{\omega_n}$ → damping ratio.

ω_n → natural freq

$\omega_d = \omega_n \sqrt{1-\zeta^2}$ → damped freq.



$s^2 + 2\zeta\omega_n s + \omega_n^2 = 0$

eg. $\frac{c(s)}{R(s)} = \frac{s+1}{2s^2+4s+6}$, $\omega_n = ?$
 $\zeta = ?$
 $\rightarrow \frac{(s+1)/2}{\underbrace{[s^2+2s+3]}}$

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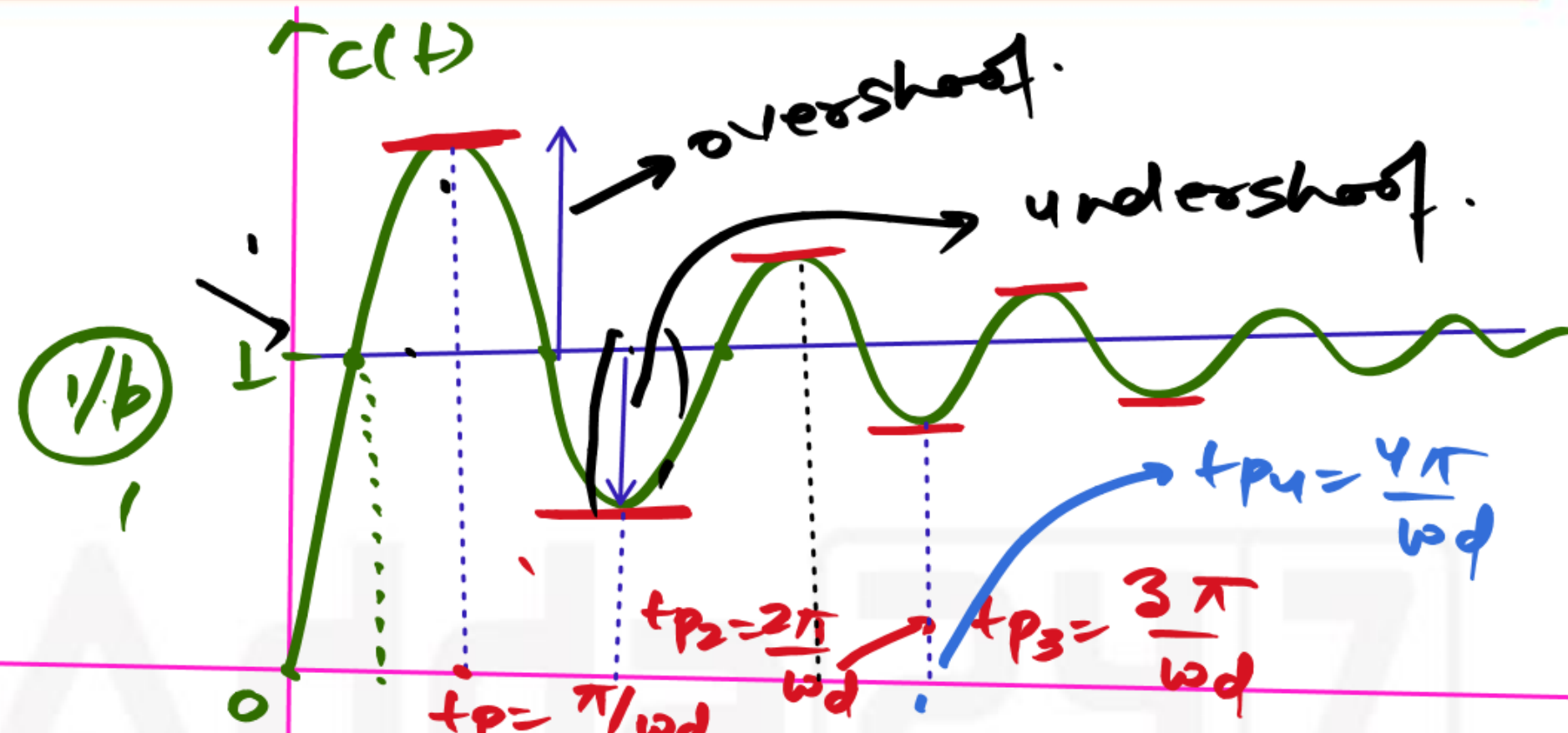
$$\underline{s^2 + 2s + 3 = 0}$$

$$s^2 + 2\zeta\omega_n s + \omega_n^2 = 0$$

$$\Rightarrow \underline{\omega_n = \sqrt{3} \text{ rad/s}}$$

$$\zeta \times \omega_n = 2$$

$$\zeta = \frac{1}{\omega_n} = \underline{\underline{\frac{1}{\sqrt{3}}}}$$



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$t_{pn} = \frac{n\pi}{\omega_d}$
 $n \rightarrow \text{odd} \rightarrow \text{overshoot}$
 $n \rightarrow \text{even} \rightarrow \text{undershoot}$

2. Peak time

$$t_{pn} = \frac{n\pi}{\omega_d} = \frac{n\pi}{\omega_n \sqrt{1-\zeta^2}}$$

1. Rise time $\theta = \cos^{-1}(\zeta)$

$t_r \rightarrow 0 - 100\%$
 Underdamp.

$$t_r = \frac{\pi - \theta}{\omega_d} = \frac{\pi - \theta}{\omega_n \sqrt{1-\zeta^2}}$$

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* Maximum overshoot

$$= \frac{c(t)_{max} - c(t)_{des.}}{c(t)_{des.}} \times 100$$

$n \rightarrow 1 \rightarrow 17.0$
 $n \rightarrow 2 \rightarrow 17.5$

In gen.: \rightarrow

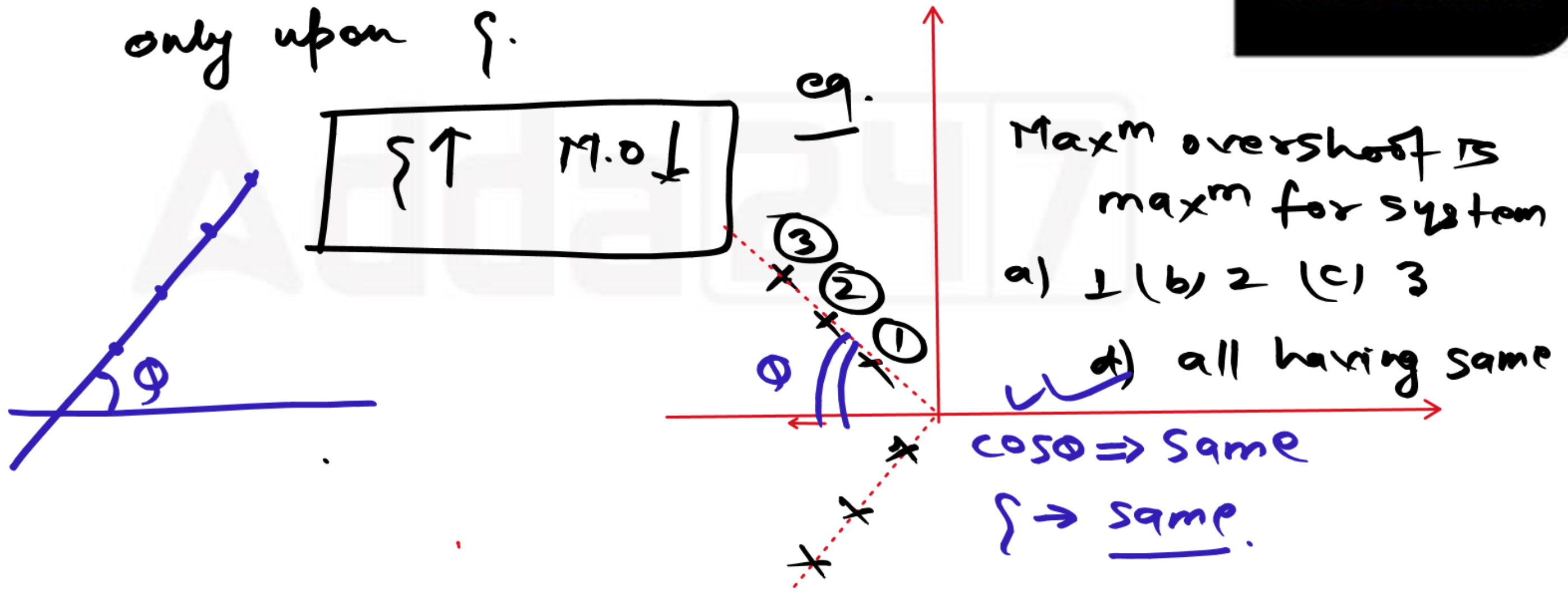
$$M.O./P.U. =$$

$$= \frac{e^{-\zeta\pi} \times 100}{e^{\frac{-n\zeta\pi}{\sqrt{1-\zeta^2}} \times 100}}$$

$n \rightarrow \text{odd}$
 \downarrow
 overshoot.
 $n \rightarrow \text{even}$
 \downarrow
 undershoot.

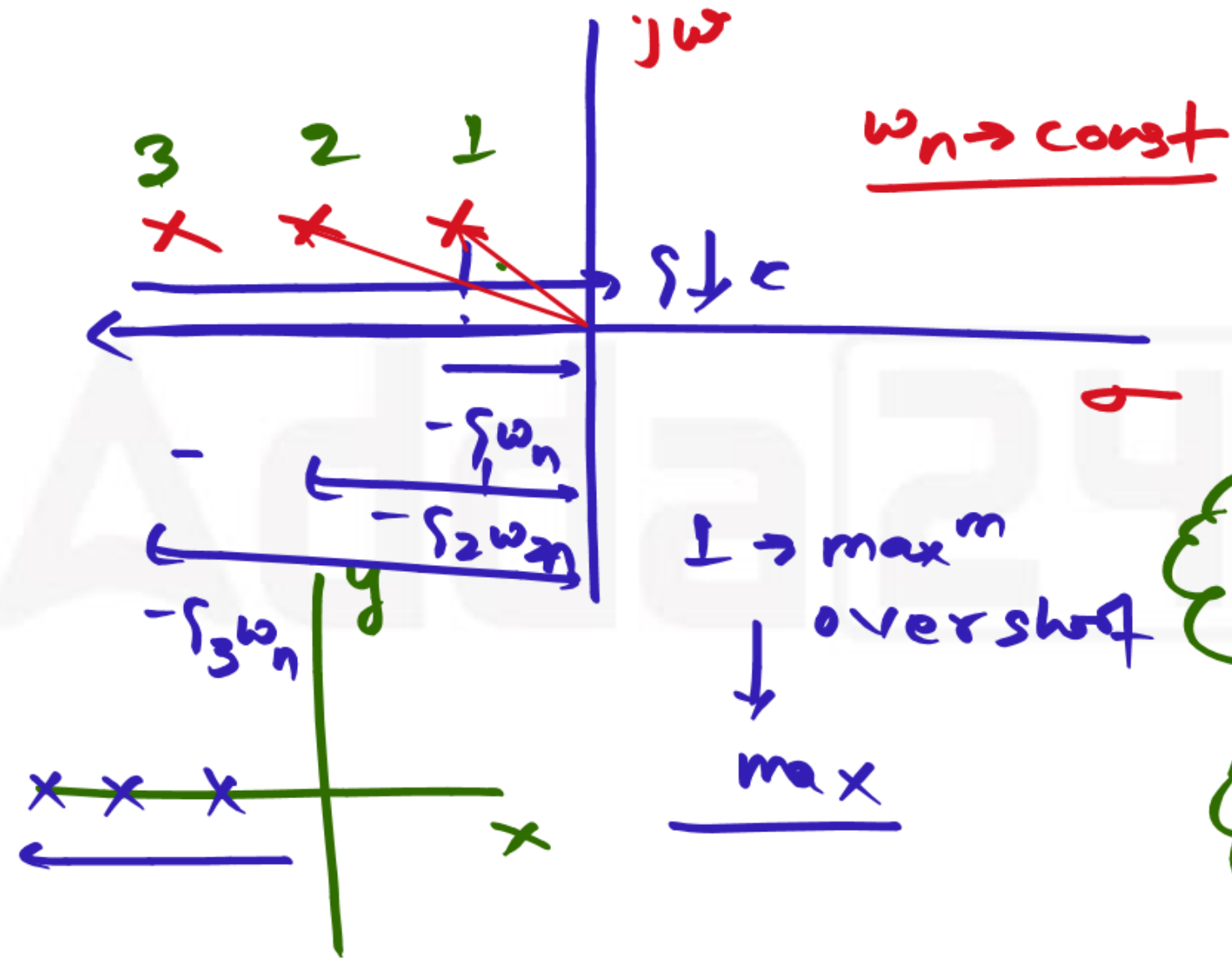
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* Max^m overshoot/undershoot depends only upon ζ .



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eg.

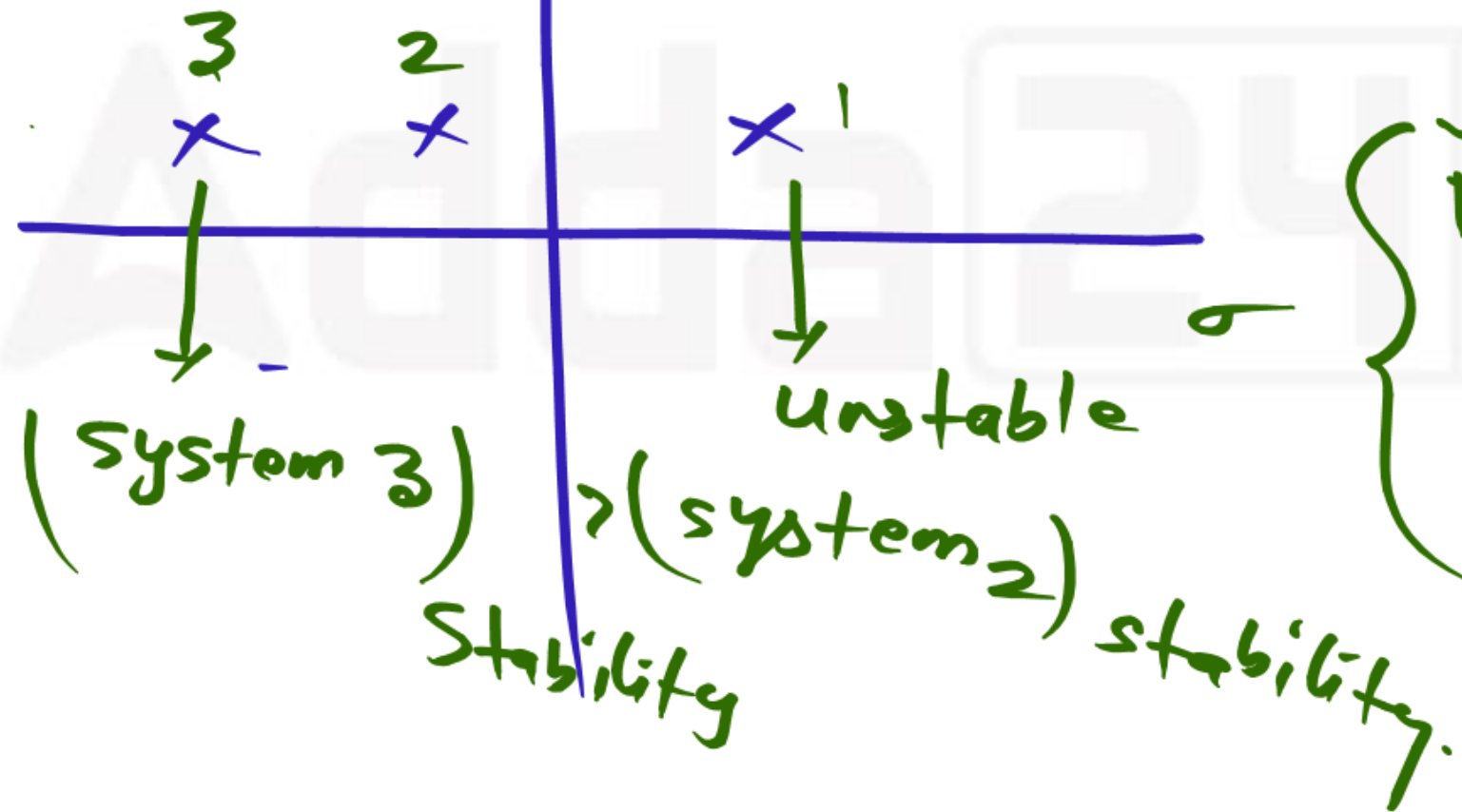
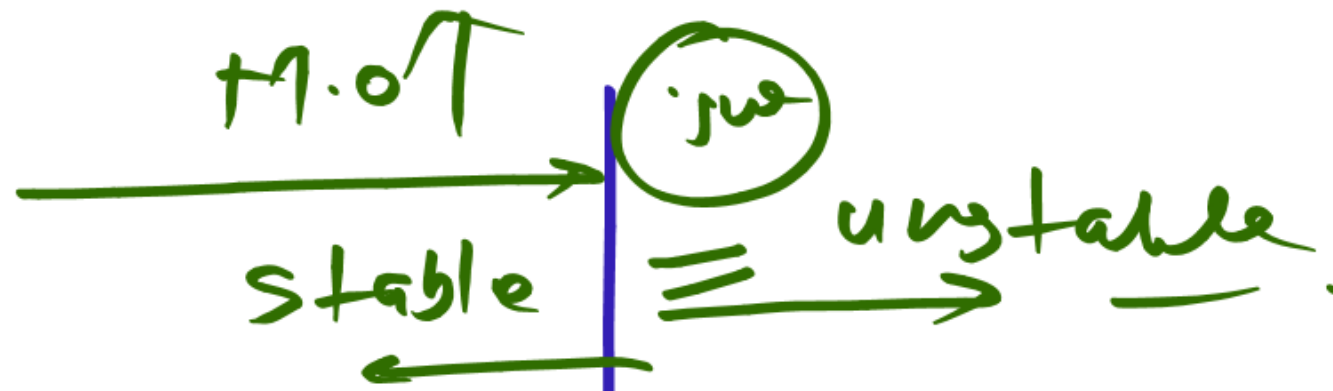


M.O depends only upon ζ .

$\zeta \downarrow \uparrow \text{M.O}$

$\zeta \uparrow \downarrow \text{M.O}$

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M.O defines relative stability.
M.O↑ relative stability↓

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