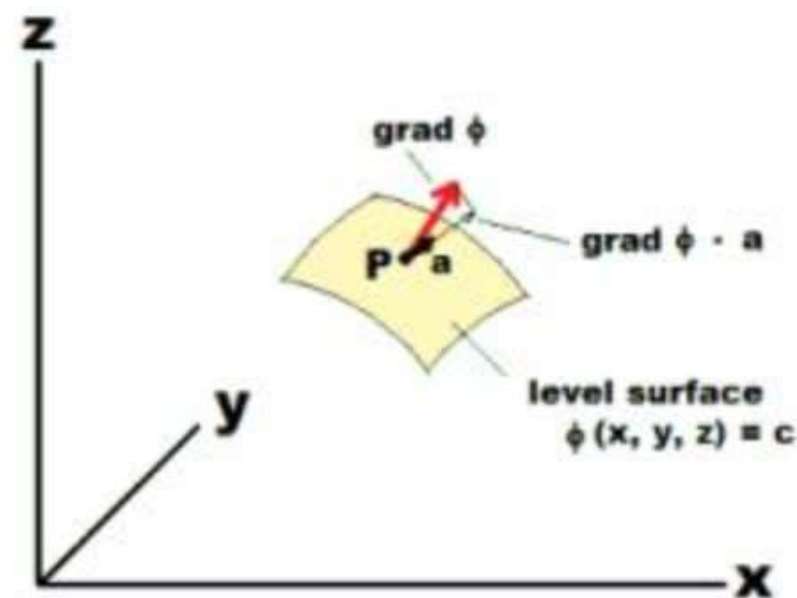




today's  
topics

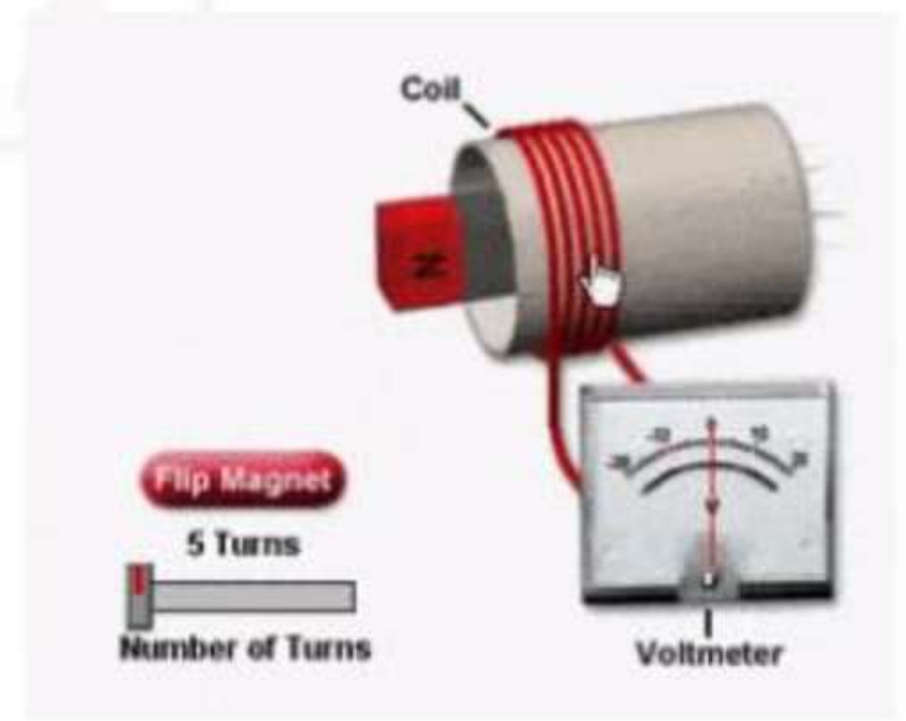
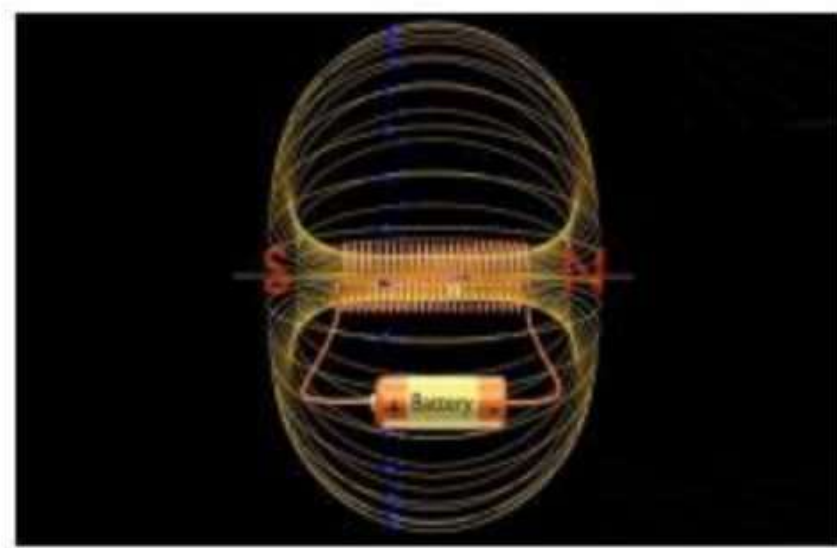
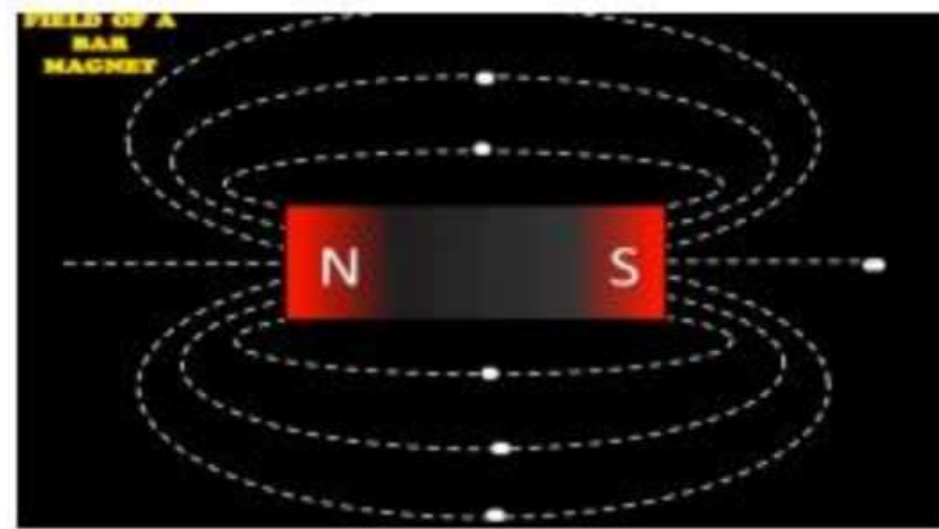
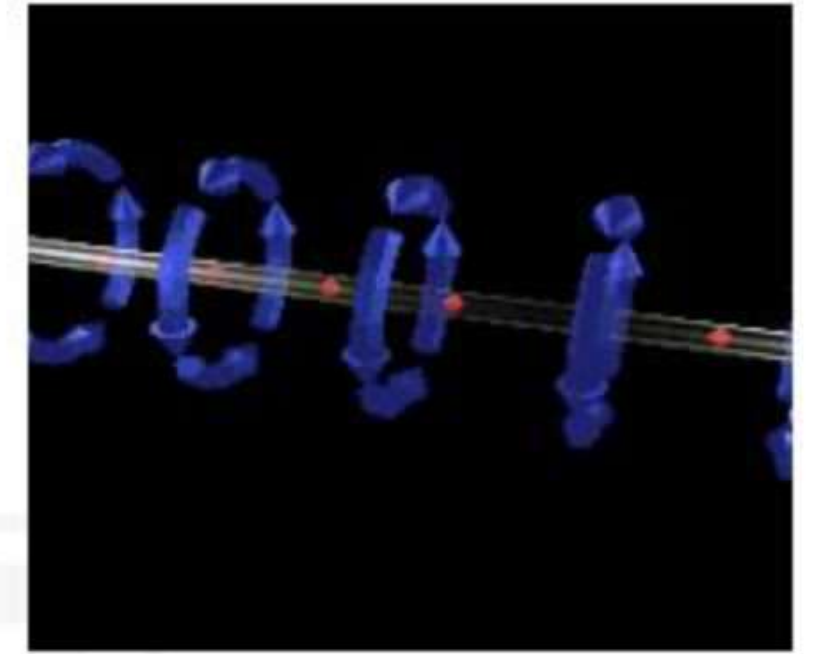
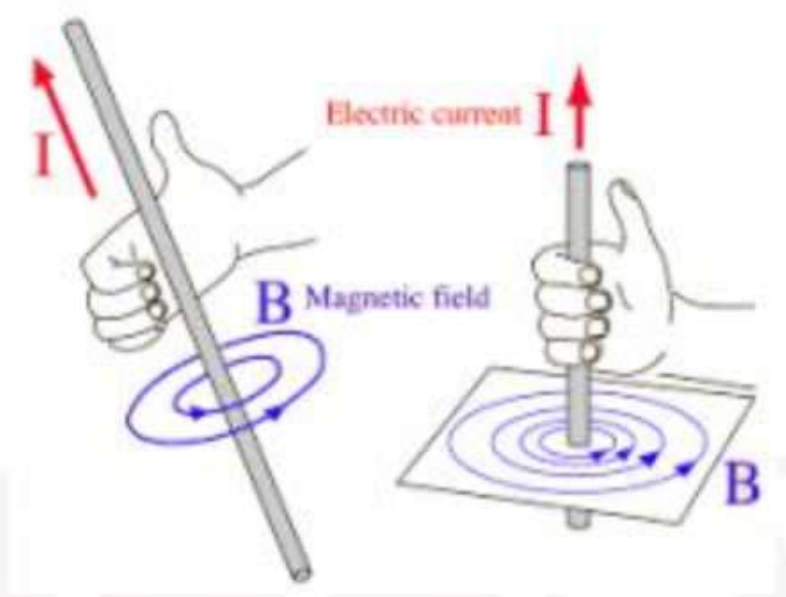
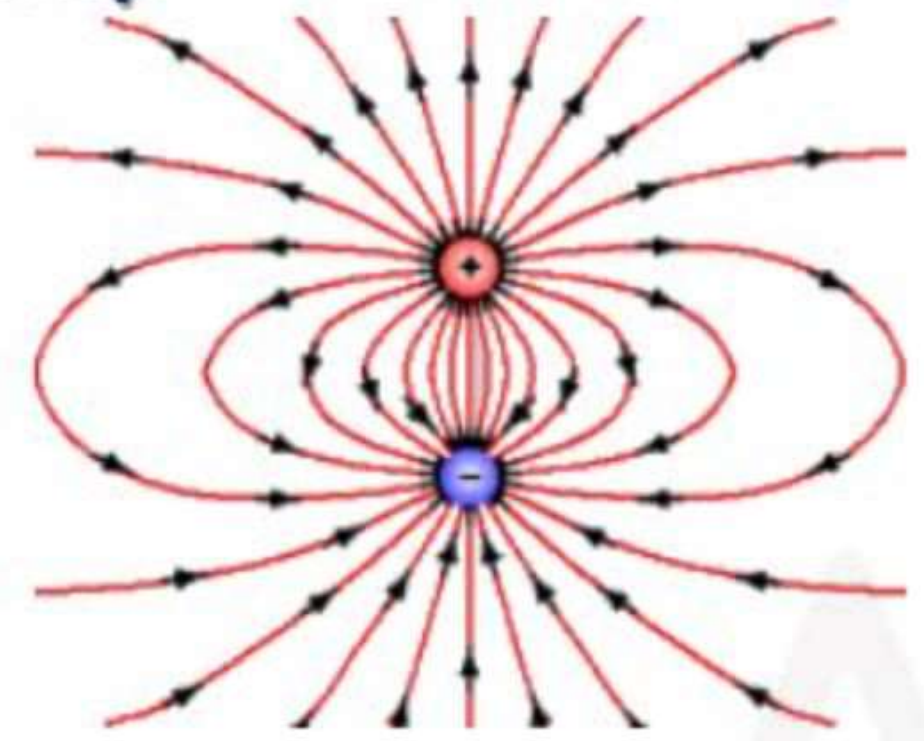
**Del Operator**

**Gradient and its Applications**



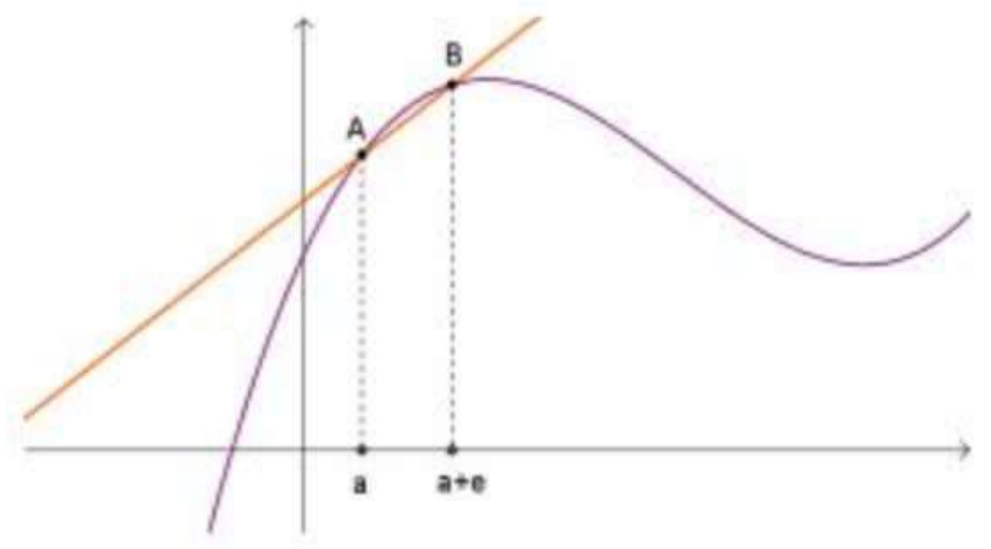
**Fig. 1**

### Recap





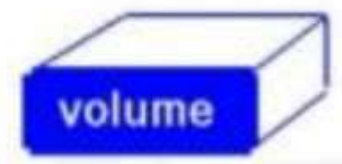
**Recap**



A scalar quantity has only **magnitude**.  
 A vector quantity has both **magnitude** and **direction**.

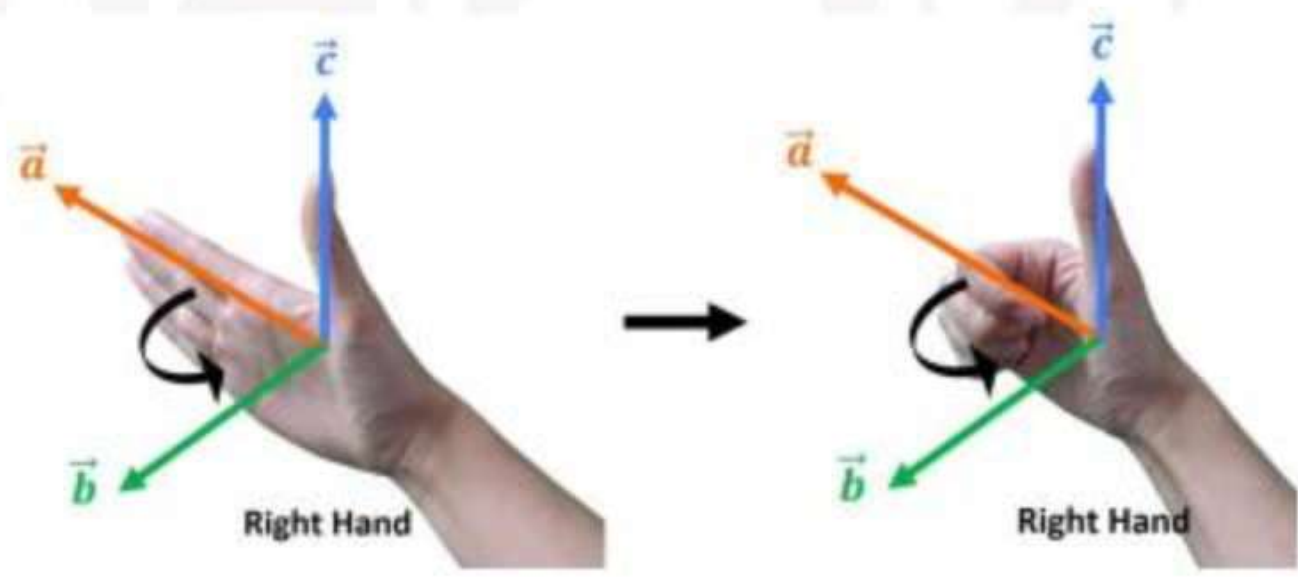
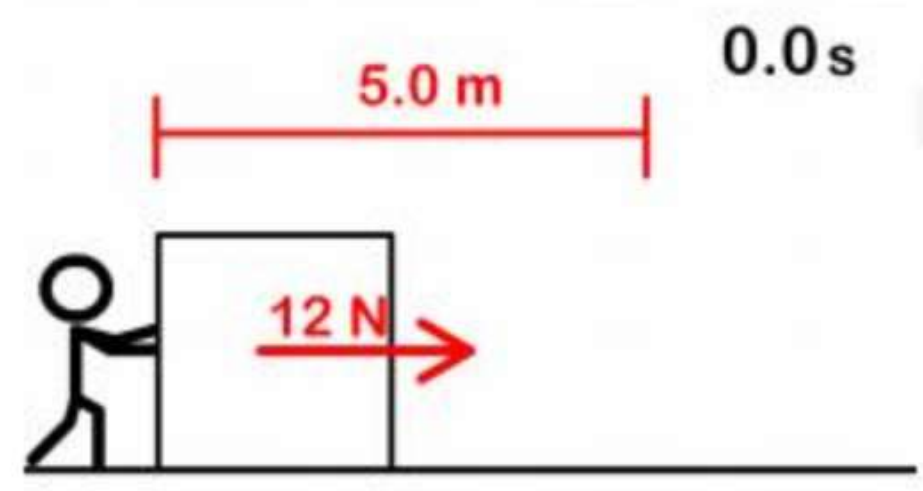
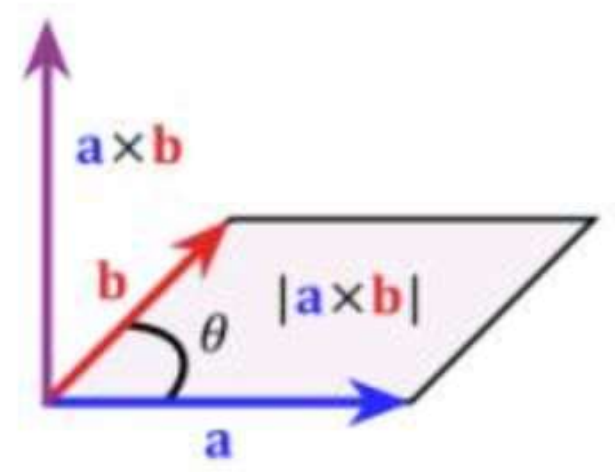
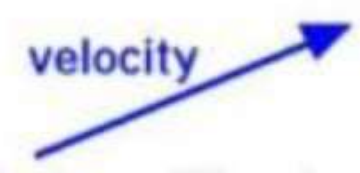
Scalar Quantities

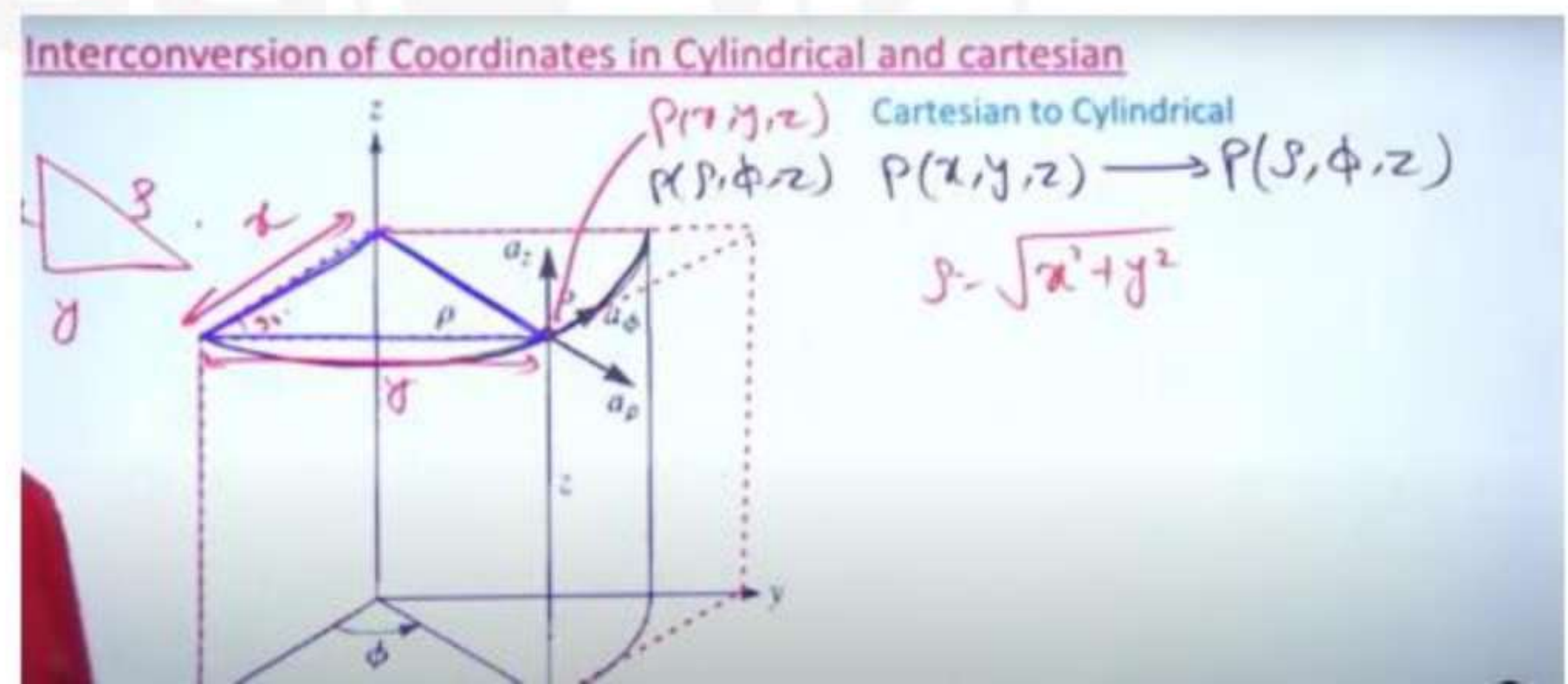
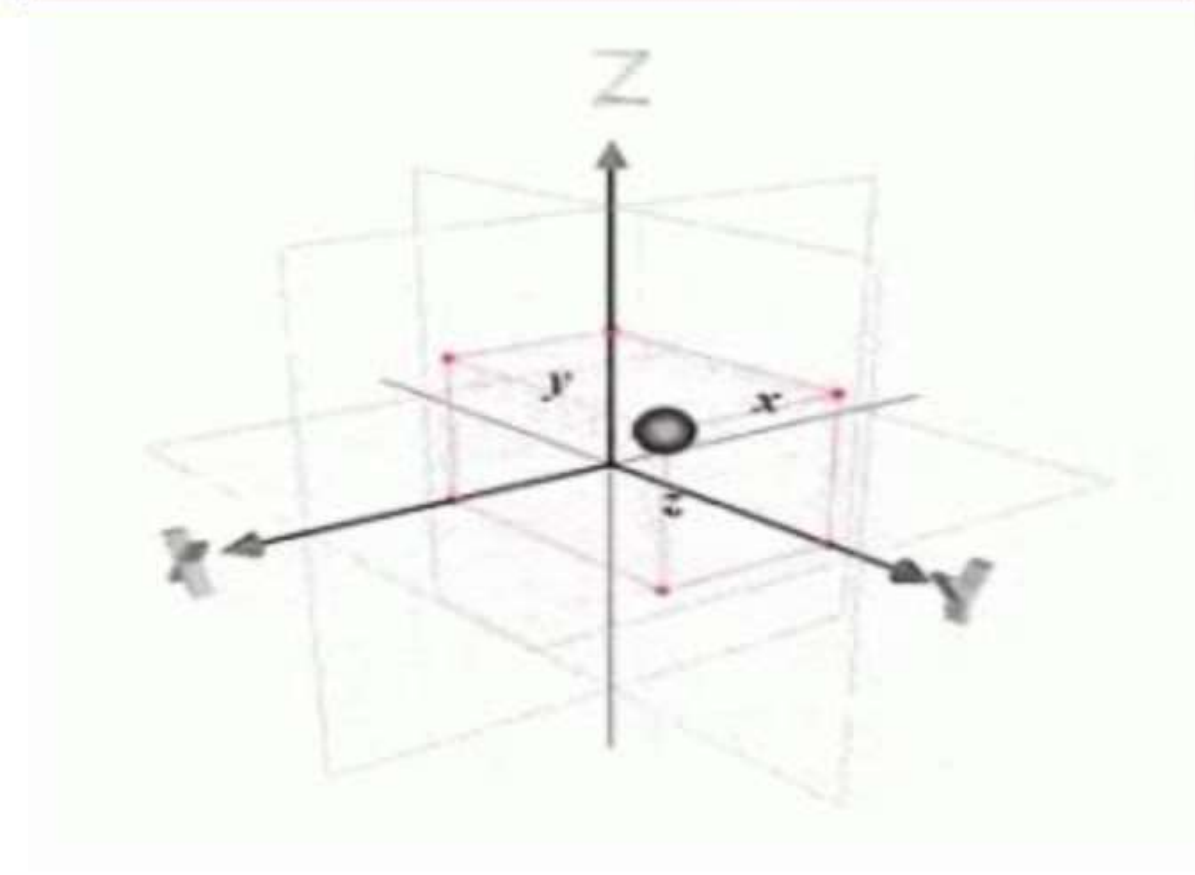
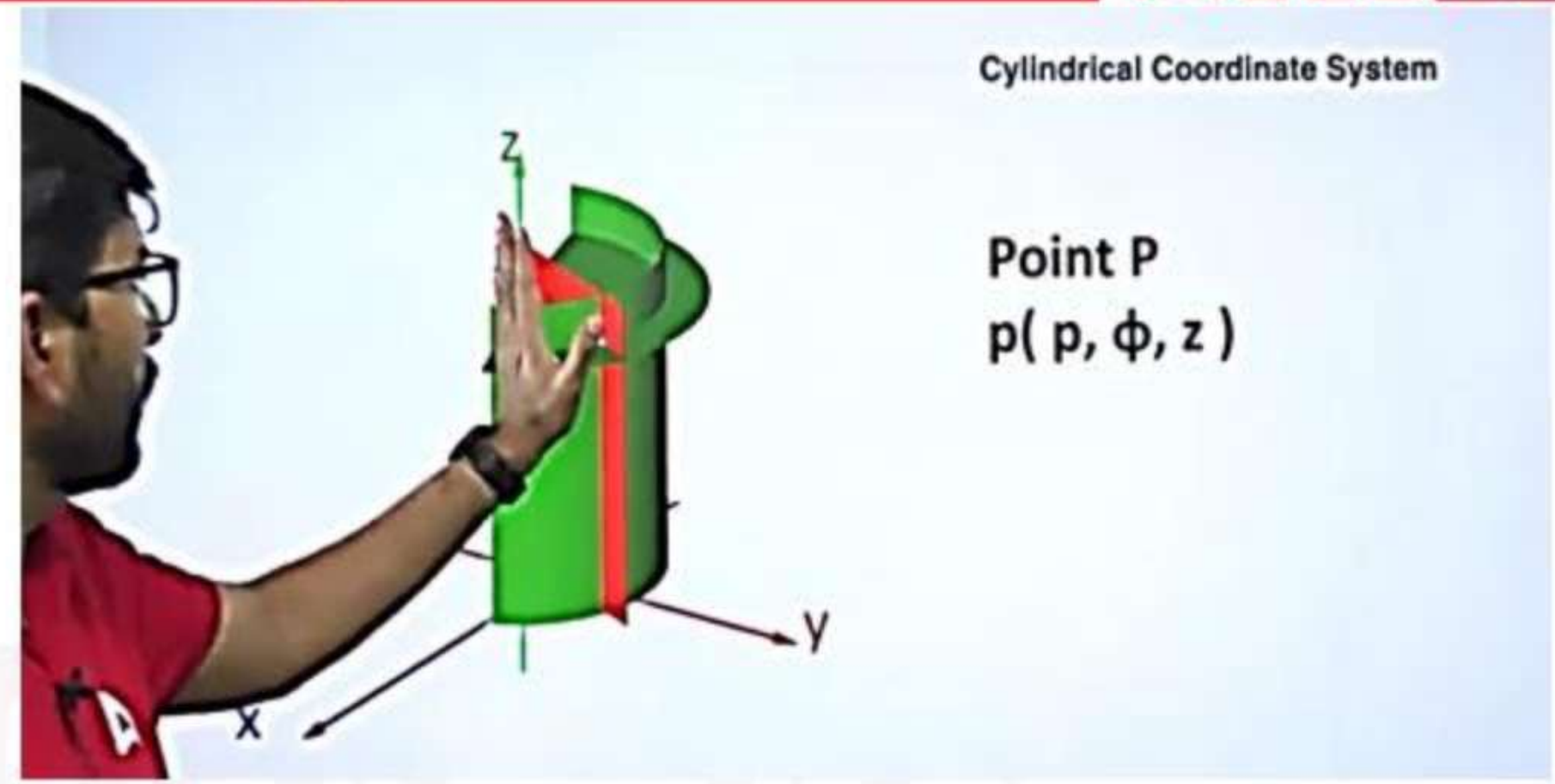
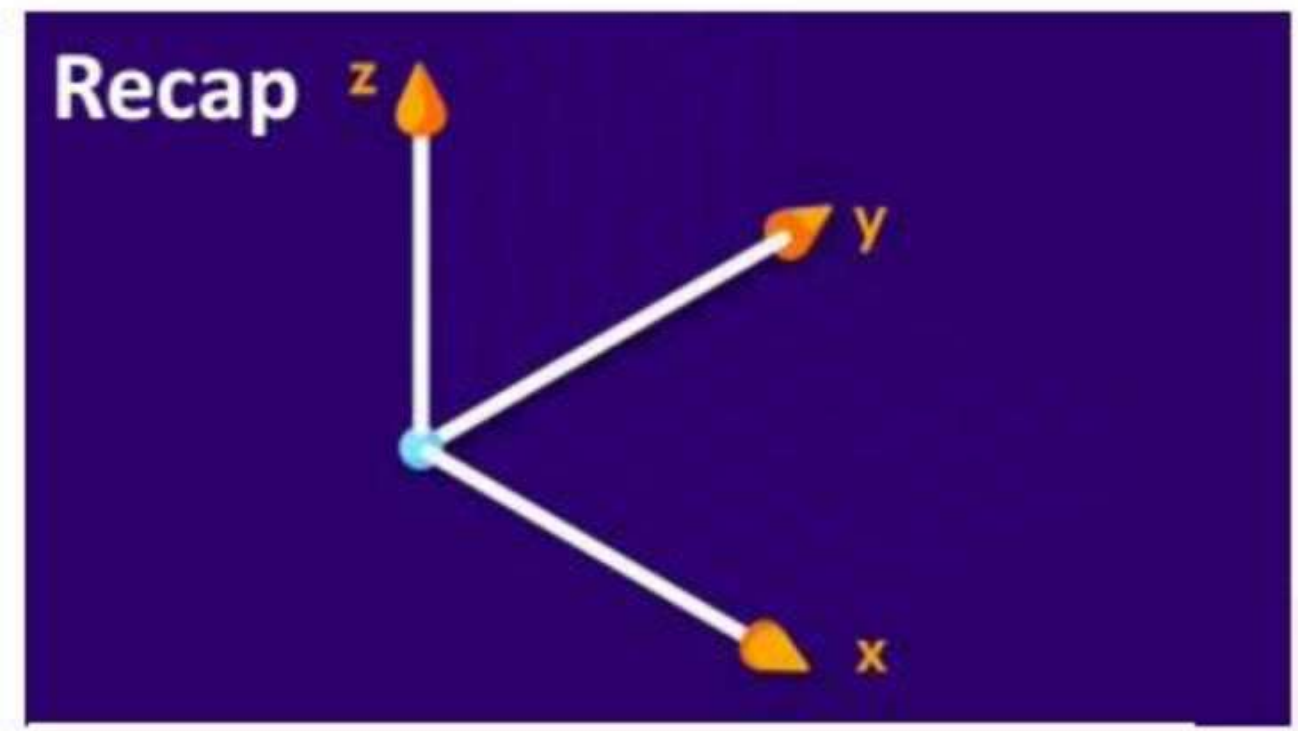
- length, area, volume
- speed
- mass, density
- pressure
- temperature
- energy, entropy
- work, power



Vector Quantities

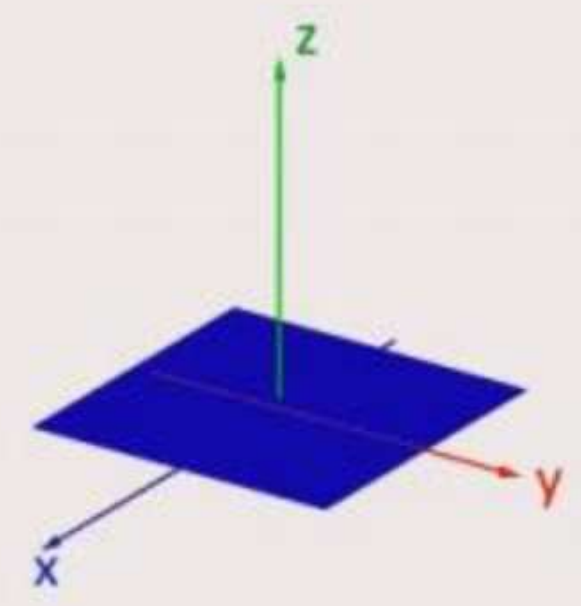
- displacement
- velocity
- acceleration
- momentum
- force
- lift, drag, thrust
- weight







Cylindrical Coordinate System



Cylindrical Coordinate System

z

Constant r  
surface

$$R \geq 0^\circ$$

y

x

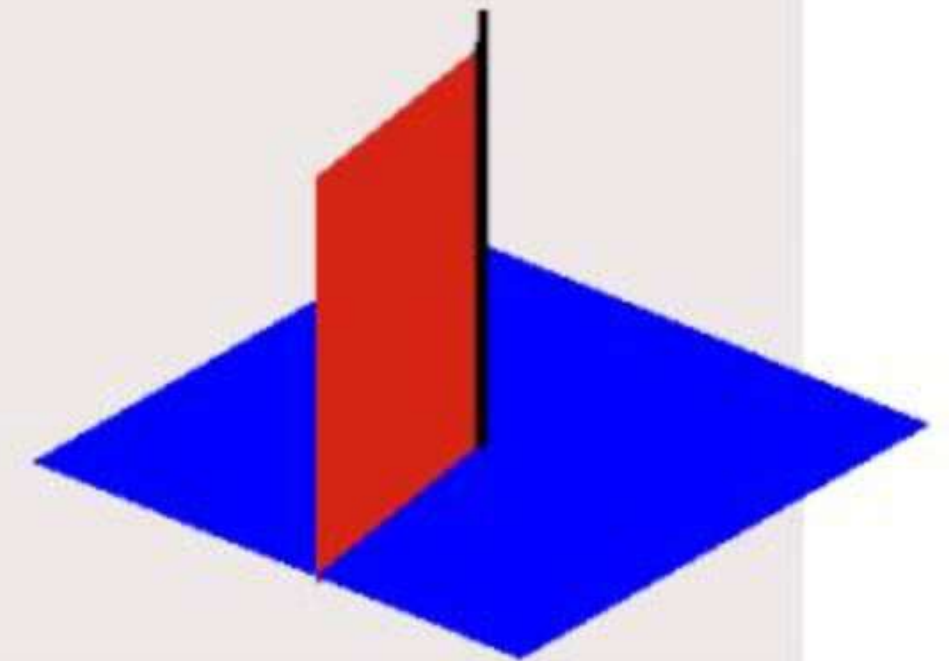
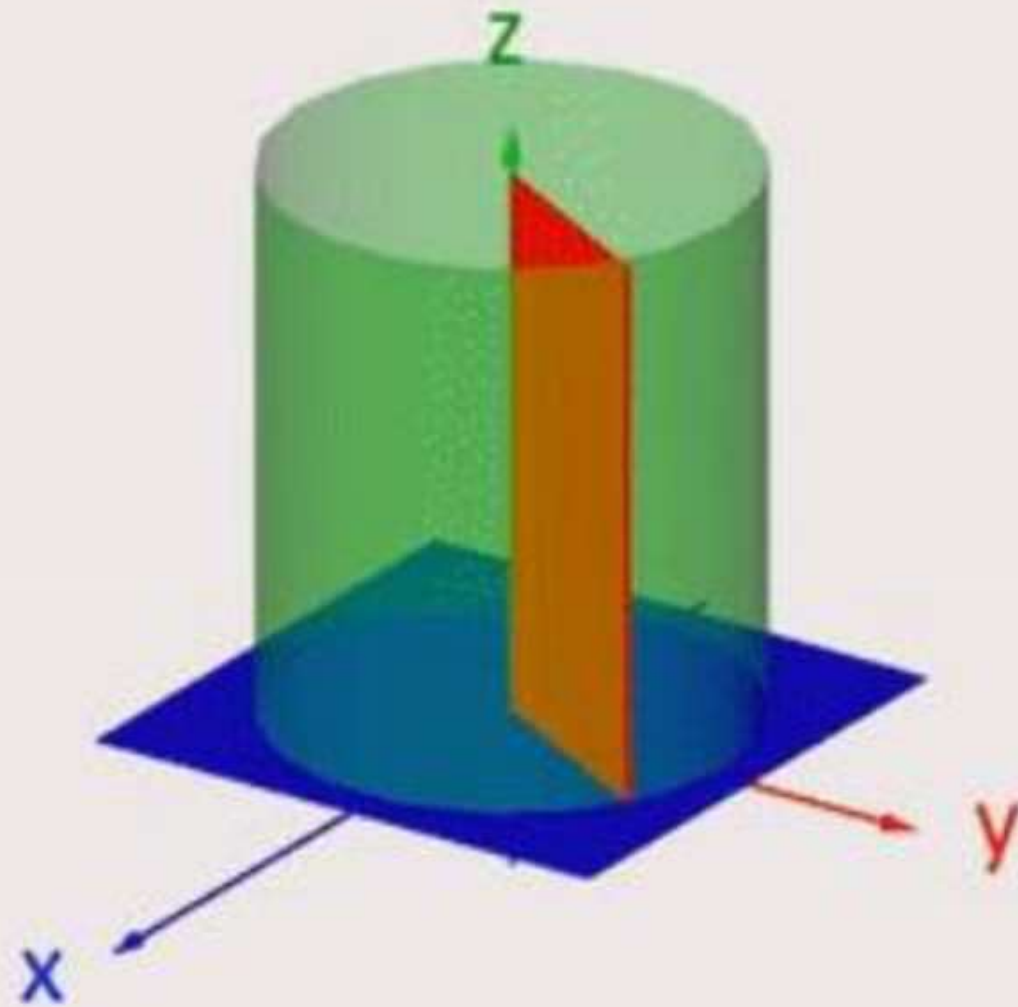
Cylindrical Coordinate System

Constant z  
surface

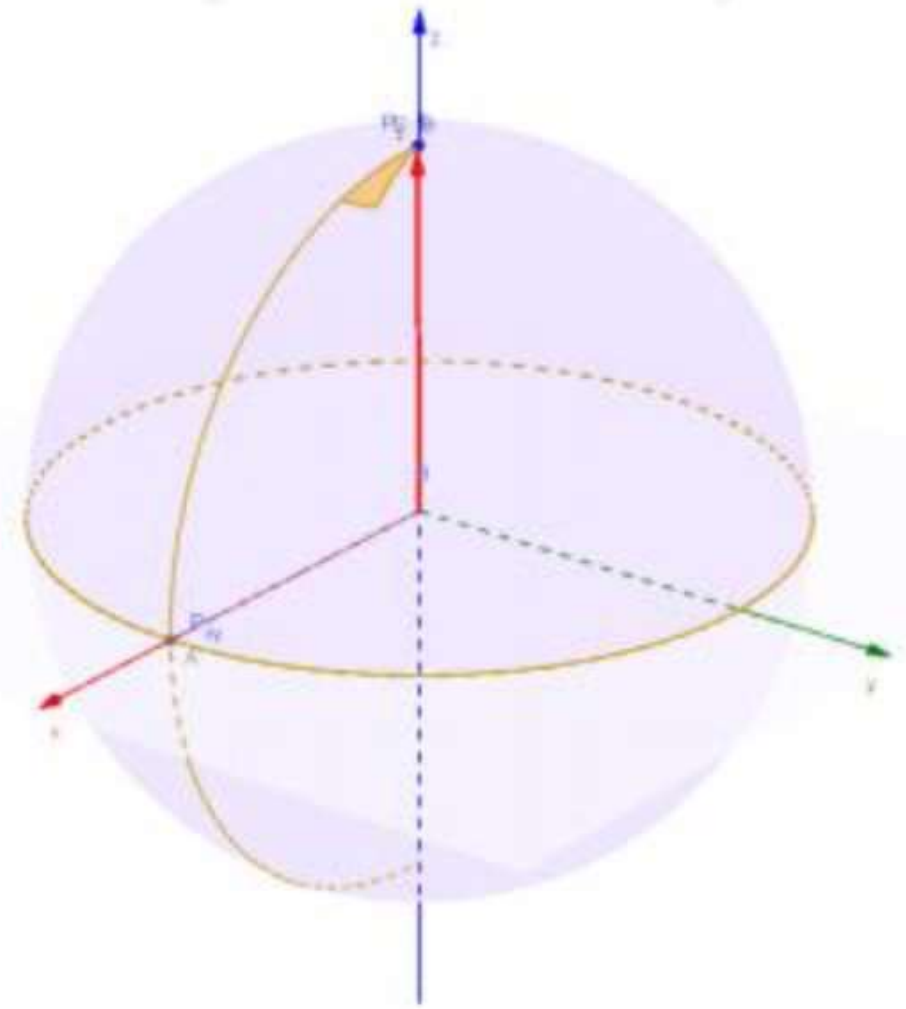
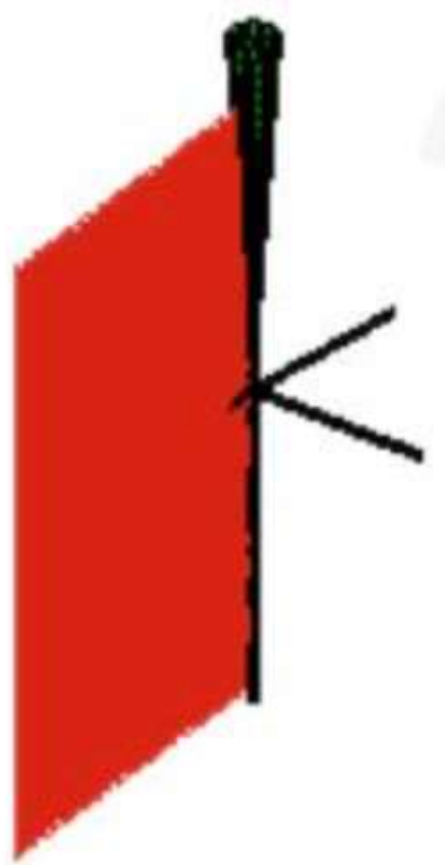
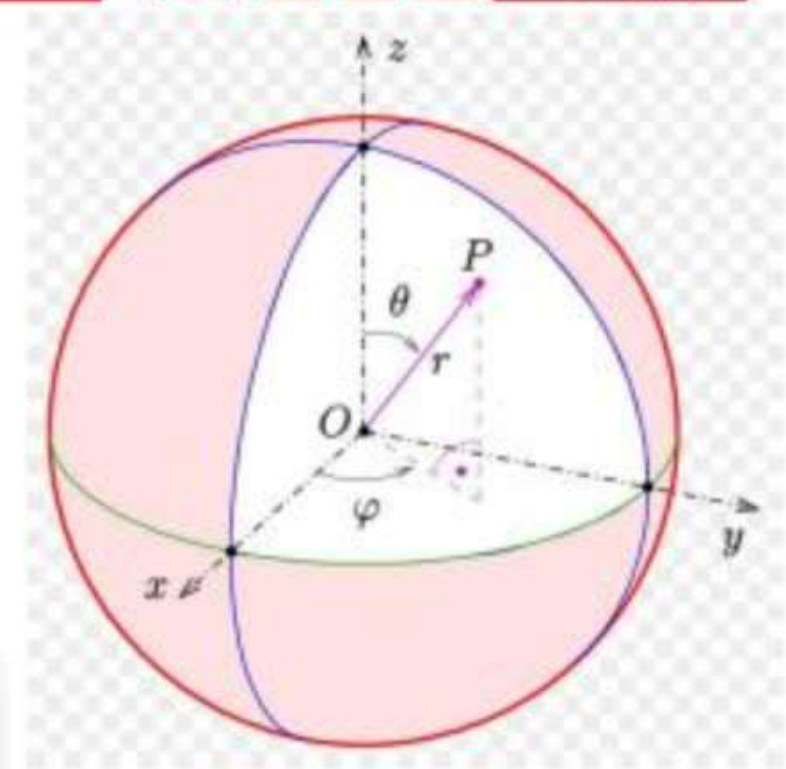
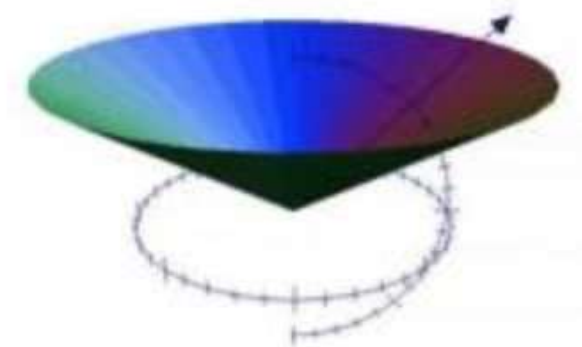
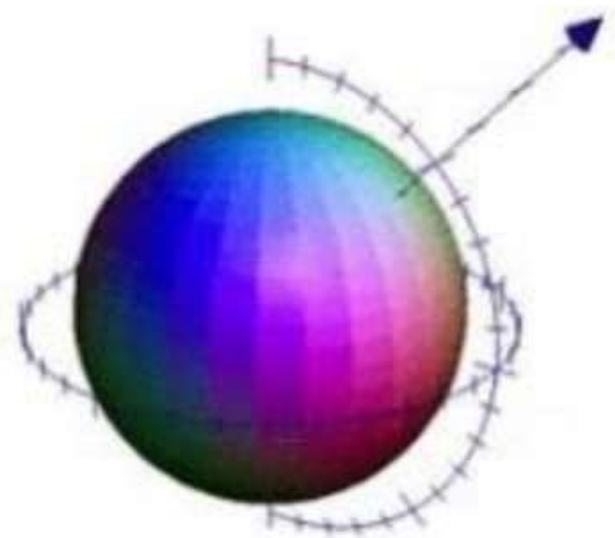
$$-\infty \leq z \leq +\infty$$

### Cylindrical Coordinate System

Cylindrical coordinate system planes



Spherical Coordinates  $P(r, \theta, \phi)$





Q.5 If  $\vec{a}$  and  $\vec{b}$  are two arbitrary vectors with magnitudes  $a$  and  $b$ , respectively,  $|\vec{a} \times \vec{b}|^2$  will be equal to

(a)  $a^2b^2 - (\vec{a} \cdot \vec{b})^2$   
 (b)  $ab - \vec{a} \cdot \vec{b}$   
 (c)  $a^2b^2 + (\vec{a} \cdot \vec{b})^2$   
 (d)  $ab + \vec{a} \cdot \vec{b}$

$\vec{a} \times \vec{b} = ab \sin \theta \hat{a}_n$   
 $|\vec{a} \times \vec{b}| = ab \sin \theta$   
 $|\vec{a} \times \vec{b}|^2 = a^2 b^2 \sin^2 \theta$  Ans  
 $\vec{a} \cdot \vec{b} = ab \cos \theta$   
 $\sin^2 \theta = 1 - \cos^2 \theta$   
 $|\vec{a} \times \vec{b}|^2 = a^2 b^2 (1 - \cos^2 \theta) = a^2 b^2 - a^2 b^2 \cos^2 \theta = a^2 b^2 - (\vec{a} \cdot \vec{b})^2$

Q.21 Evaluate  $\int_C \vec{F} \cdot d\vec{r}$  where  $\vec{F} = \frac{y\hat{i} - x\hat{j}}{x^2 + y^2}$

(i) Circular path  $x^2 + y^2 = 1$  described clockwise.  
 (ii) The square formed by the lines  $x = \pm 1, y = \pm 1$ , counter clockwise.

(i)  $\oint_C \frac{y dx - x dy}{x^2 + y^2}$   
 $= \int_0^{2\pi} \frac{-\sin^2 \theta}{1} d\theta$   
 $= \int_0^{2\pi} -\sin^2 \theta d\theta = -\pi$

(ii)  $\oint_C \frac{y dx - x dy}{x^2 + y^2}$   
 $= \int_0^1 \int_{-1}^1 \frac{-x dy}{x^2 + y^2} dx + \int_1^0 \int_{-1}^1 \frac{y dx}{x^2 + y^2} dy + \int_0^1 \int_{-1}^1 \frac{x dy}{x^2 + y^2} dx + \int_{-1}^0 \int_{-1}^1 \frac{-y dx}{x^2 + y^2} dy$   
 $= 0 + 0 + 0 + 0 = 0$

## Number of Questions covered-22

Q.6 For the parallelogram OPQR shown in the sketch,  $\vec{OP} = a\hat{i} + b\hat{j}$  and  $\vec{OR} = c\hat{i} + d\hat{j}$ . The area of the parallelogram is.

(a)  $ad - bc$   
 (b)  $ac + bd$   
 (c)  $ad + bc$   
 (d)  $ab - cd$

$\vec{A} \times \vec{B} = \vec{OP} \times \vec{OR} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ a & b & 0 \\ c & d & 0 \end{vmatrix} = (ad - bc)\hat{k}$

$\text{Area} = |\vec{A} \times \vec{B}| = |ad - bc|$

Q.7 P, Q and R are three points having coordinates  $(3, -2, -1)$ ,  $(1, 3, 4)$ ,  $(2, 1, -2)$  in XYZ space, then the distance from point P to plane OQR (O being the origin of the coordinate system) is given by

$\vec{OQ} \times \vec{OR} = \vec{X}$

$\vec{OQ} = \hat{i} + 3\hat{j} + 4\hat{k}$ ,  $\vec{OR} = 2\hat{i} + \hat{j} - 2\hat{k}$

$\vec{OQ} \times \vec{OR} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 1 & 3 & 4 \\ 2 & 1 & -2 \end{vmatrix} = (-10)\hat{i} + 10\hat{j} + 5\hat{k}$

Distance =  $\frac{|\vec{OP} \cdot \vec{X}|}{|\vec{X}|} = \frac{|(3\hat{i} - 2\hat{j} - \hat{k}) \cdot (-10\hat{i} + 10\hat{j} + 5\hat{k})|}{\sqrt{100 + 100 + 25}} = \frac{|-30 - 20 - 5|}{\sqrt{225}} = \frac{55}{15} = \frac{11}{3}$

**HATE**  
**AAI ATC**  
 1 mark - 1480  
 2 mark - 336



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# GATE 2024



**प्रचण्ड** Batch

**Electromagnetic Field Theory**

**DEL OPERATOR, GRADIENT  
AND ITS APPLICATIONS**

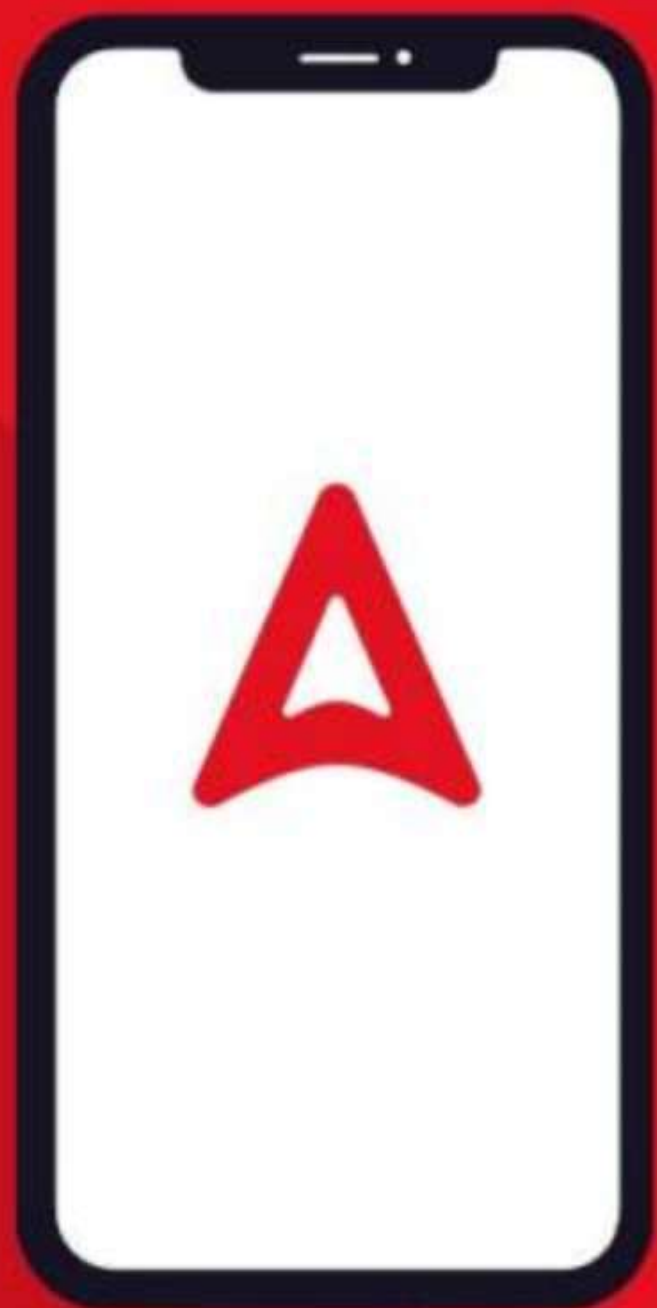
**LEC-07**

**EE & ECE**





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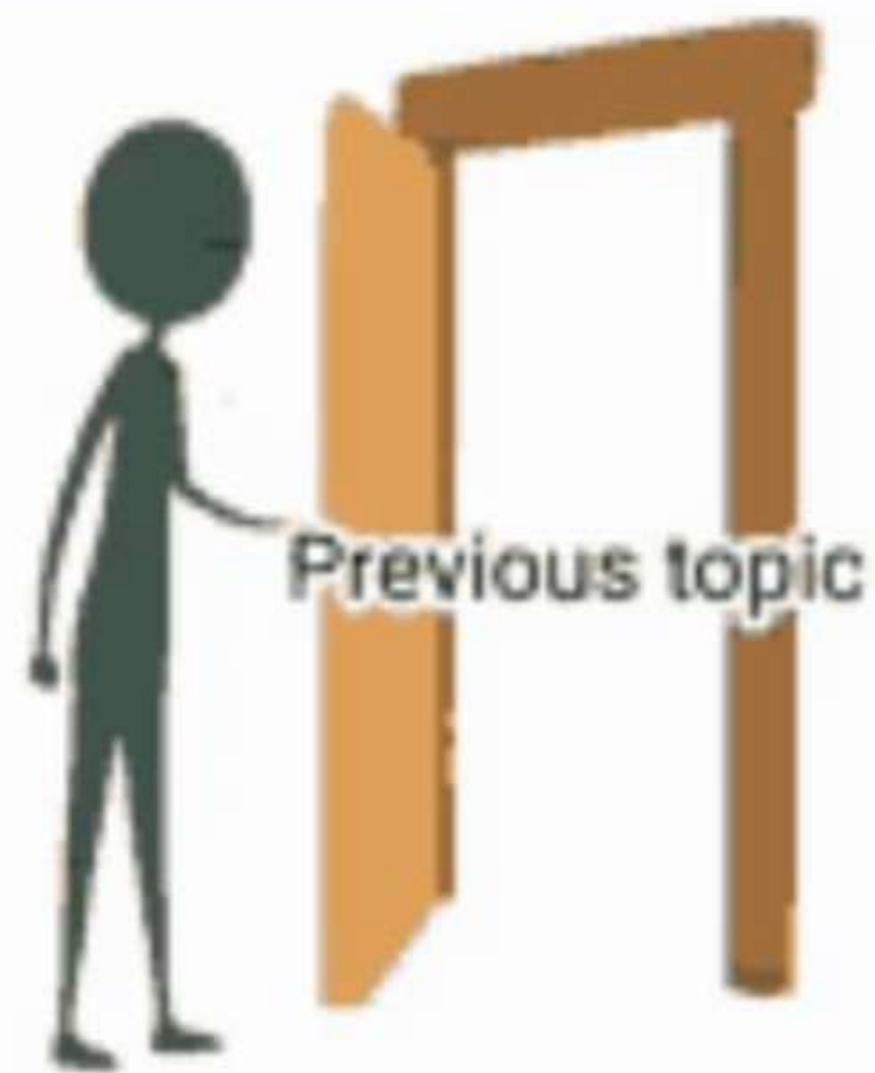
**Power Capsule**



**Notes & Articles**



**Videos**



- 1. Basic introduction of Fields**
- 2. Vectors, Scalars and Tensors**
- 3. Position vector and vector between points**
- 4. Magnitude and direction of vector**
- 5. Dot and cross products and its applications**
- 6. Cartesian and Cylindrical and Spherical Coordinate systems**
- 7. Vector integrals( Line and closed line)**

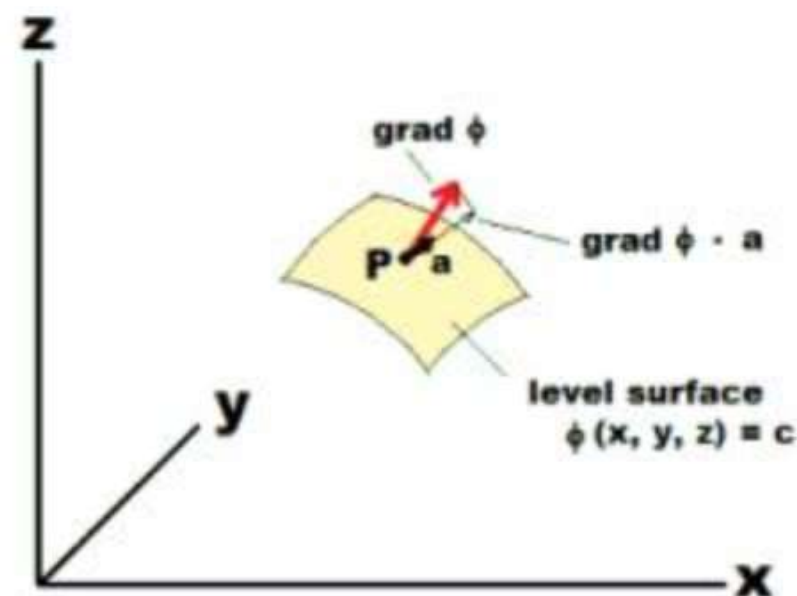




today's  
topics

**Del Operator**

**Gradient and its Applications**



**Fig. 1**

Del Operator:- It is differential operator in Vector calculus.

- ❖ Del operator is first order differential operator.
- ❖ Line integral is first order integral.
- ❖ Del Operator is a vector.
- ❖ Del operator symbol is named as Nabla.

$$\frac{d(f(x))}{dx}$$

$$\frac{\partial f(x,y)}{\partial y}$$

$$\int \vec{A} \cdot \underline{d\vec{l}} = \int (A_x \hat{i} + A_y \hat{j} + A_z \hat{k}) \cdot \nabla (dx \hat{i} + dy \hat{j} + dz \hat{k}) = \int A_x dx + \int A_y dy + \int A_z dz$$

$$\int \vec{A} \cdot \vec{ds} = \int A_x dy dz$$

$$\int \rho_v dv = \int \rho_v dx dy dz$$

line integral → single order  
 surface → double integral  
 Volume → triple integral.



Del Operator in Cartesian Coordinate Systems

$$\vec{dl} = dx \hat{a}_x + dy \hat{a}_y + dz \hat{a}_z$$

$$\nabla = \frac{\partial}{\partial x} \hat{a}_x + \frac{\partial}{\partial y} \hat{a}_y + \frac{\partial}{\partial z} \hat{a}_z$$

$\int \dots dx$   
 $\frac{d}{dz}$   
 $\int f(x,y) dy$   
 $\frac{f_x}{e}$

## Del Operator in Cylindrical Coordinate Systems

$$d\vec{l} = dr \hat{a}_r + r d\phi \hat{a}_\phi + dz \hat{a}_z$$

$$\nabla = \frac{\partial}{\partial r} \hat{a}_r + \frac{1}{r} \frac{\partial}{\partial \phi} \hat{a}_\phi + \frac{\partial}{\partial z} \hat{a}_z$$



## Del Operator in Spherical Coordinate Systems

$$d\vec{l} = dr \hat{q}_r + r d\theta \hat{q}_\theta + r \sin\theta d\phi \hat{q}_\phi$$

$$\nabla = \frac{\partial}{\partial r} \hat{q}_r + \frac{1}{r} \frac{\partial}{\partial \theta} \hat{q}_\theta + \frac{1}{r \sin\theta} \frac{\partial}{\partial \phi} \hat{q}_\phi$$

$\nabla \rightarrow$  It is vector.

## First Order Differential Operations using Del operator

①  $\nabla v \rightarrow$  Gradient

②  $\nabla \cdot \vec{A} \rightarrow$  Divergence

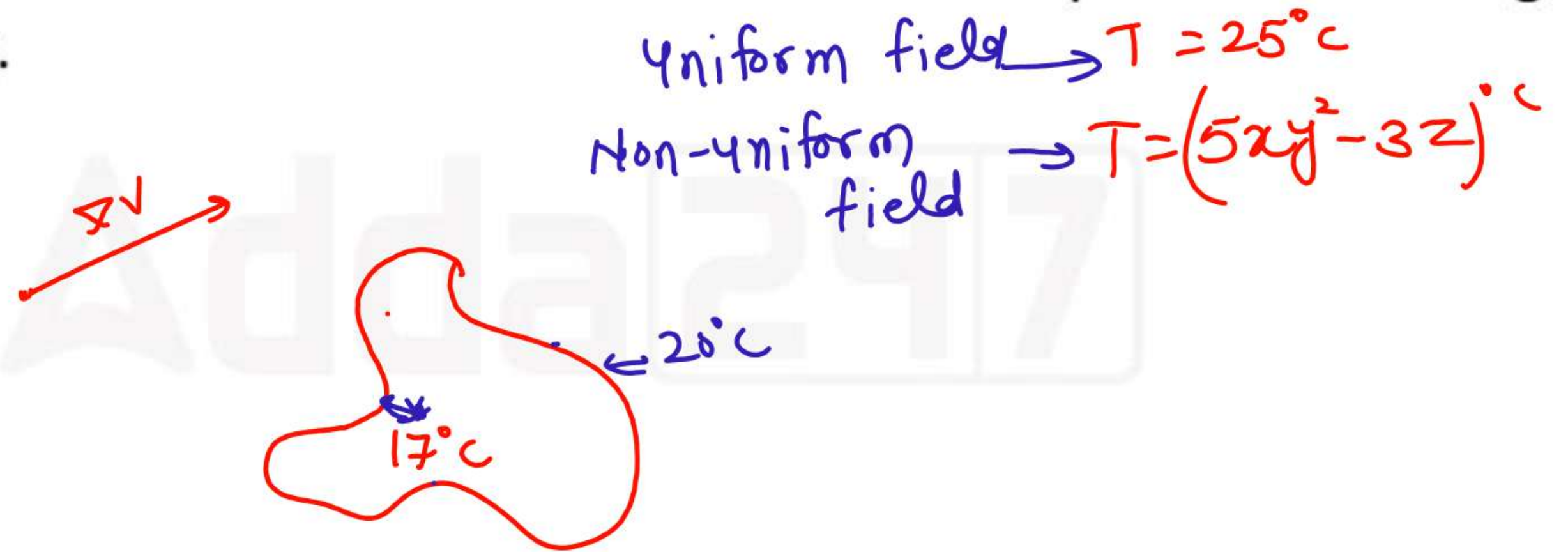
③  $\nabla \times \vec{A} \rightarrow$  Curl

\* Gradient operation is performed on Scalars.

\* Gradient results a vector.



**Gradient**:- Gradient of a non uniform scalar field at a point is a vector, of which magnitude is maximum space rate of change at the point and its direction is in the direction in which maximum space rate of change occurs.



**Q:23** Temperature in an auditorium is given by  $T=15x^2yz^3$ . A mosquito located At point  $(-1,2,4)$  feels cold , in which direction it must fly to get relax?

sol: → direction of gradient

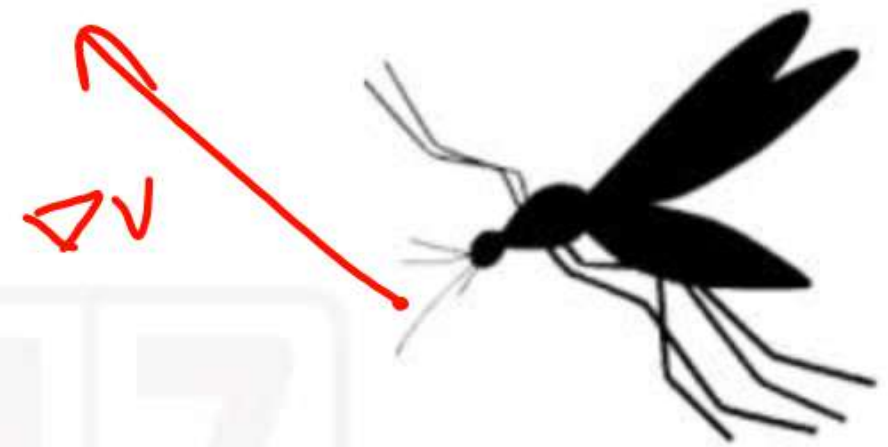
= unit vector of gradient

$$= \frac{\nabla T}{|\nabla T|} \quad T = 15x^2yz^3$$

$$\nabla T = 30xyz^3 \hat{i} + 15x^2z^3 \hat{j} + 45x^2yz^2 \hat{k}$$

$$\nabla T|_{(-1,2,4)} = -60 \times 64 \hat{i} + 15 \times 64 \hat{j} + 90 \times 16 \hat{k}$$

$$\text{direction} = \frac{-60 + 64 \hat{i} + 15 \times 64 \hat{j} + 90 \times 16 \hat{k}}{\sqrt{(-60)^2 + (64)^2 + (1440)^2}}$$





## Calculation of Gradient in Cartesian Coordinate systems

$$\nabla = \frac{\partial}{\partial x} \hat{q}_x + \frac{\partial}{\partial y} \hat{q}_y + \frac{\partial}{\partial z} \hat{q}_z$$

$$V(x, y, z)$$

$$\nabla V = \left( \frac{\partial}{\partial x} \hat{q}_x + \frac{\partial}{\partial y} \hat{q}_y + \frac{\partial}{\partial z} \hat{q}_z \right) V(x, y, z)$$

$$\nabla V = \frac{\partial V}{\partial x} \hat{q}_x + \frac{\partial V}{\partial y} \hat{q}_y + \frac{\partial V}{\partial z} \hat{q}_z$$

$\nabla V \Big|_{P(x_1, y_1, z_1)} \rightarrow$  gradient at the point 'P'.

$$\vec{A} = 2\hat{i} + \hat{j} - \hat{k}$$

$$\vec{B} = 2x^2\hat{i} - 3x\hat{j} + 2y^2z\hat{k}$$

Calculation of Gradient in Cylindrical Coordinate systems  $v(\rho, \phi, z)$ 

$$\nabla = \frac{\partial}{\partial \rho} \hat{q}_\rho + \frac{1}{\rho} \frac{\partial}{\partial \phi} \hat{q}_\phi + \frac{\partial}{\partial z} \hat{q}_z$$

$$\nabla v = \frac{\partial v}{\partial \rho} \hat{q}_\rho + \frac{1}{\rho} \frac{\partial v}{\partial \phi} \hat{q}_\phi + \frac{\partial v}{\partial z} \hat{q}_z$$



Calculation of Gradient in Spherical Coordinate systems  $V(r, \theta, \phi)$ 

$$\nabla = \frac{\partial}{\partial r} \hat{q}_r + \frac{1}{r} \frac{\partial}{\partial \theta} \hat{q}_\theta + \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} \hat{q}_\phi$$

$$\nabla V = \frac{\partial V}{\partial r} \hat{q}_r + \frac{1}{r} \frac{\partial V}{\partial \theta} \hat{q}_\theta + \frac{1}{r \sin \theta} \frac{\partial V}{\partial \phi} \hat{q}_\phi$$

## Applications of Gradient

1. ✓ To find maximum rate of change and its direction at any point ✓
2. To find Directional Derivative ??
3. To find vector normal to a curve or surface at any point ??



## **DIRECTIONAL DERIVATIVE**

$$\frac{dy}{dz} = \frac{\Delta y}{\Delta z}$$

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1,

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## **DIRECTIONAL DERIVATIVE**

Application of gradient

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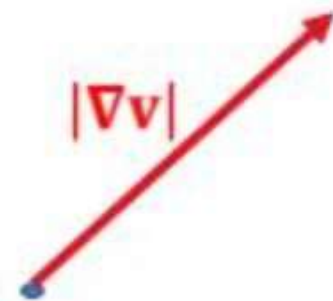
## **DIRECTIONAL DERIVATIVE**

Application of gradient



## DIRECTIONAL DERIVATIVE

Application of gradient

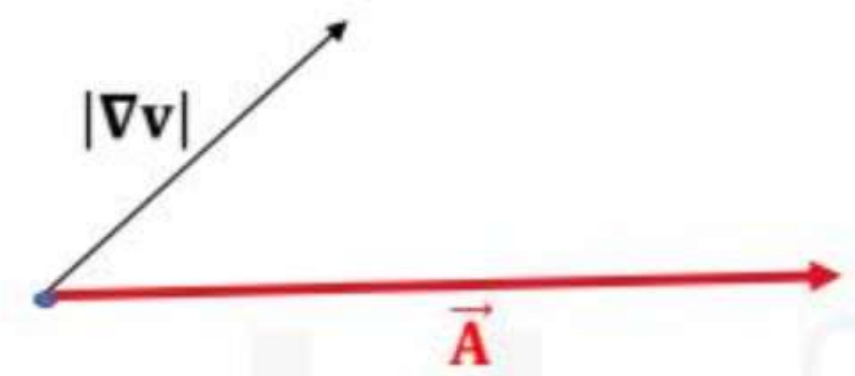


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# DIRECTIONAL DERIVATIVE

Application of gradient

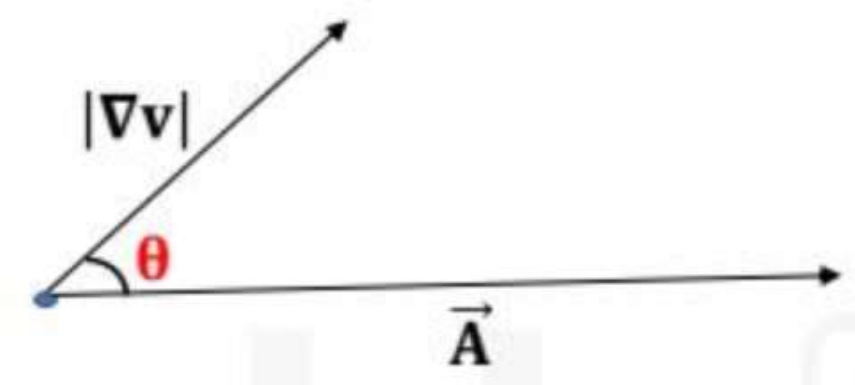


directional derivative of  $v$  in the direction of  $\vec{A}$

—

# DIRECTIONAL DERIVATIVE

Application of gradient

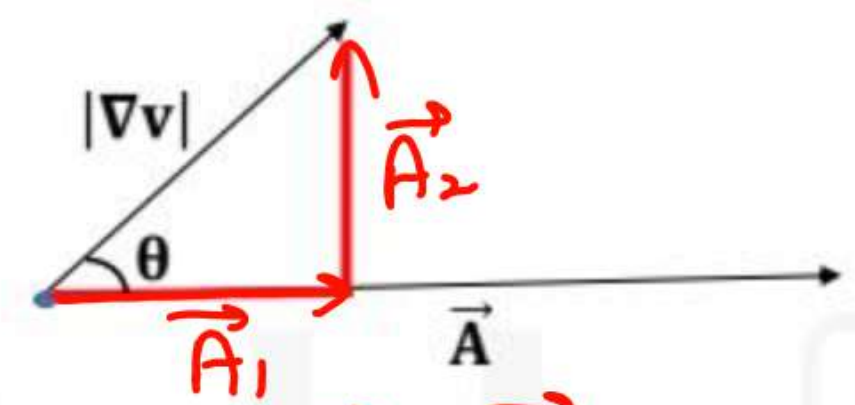


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# DIRECTIONAL DERIVATIVE

Application of gradient

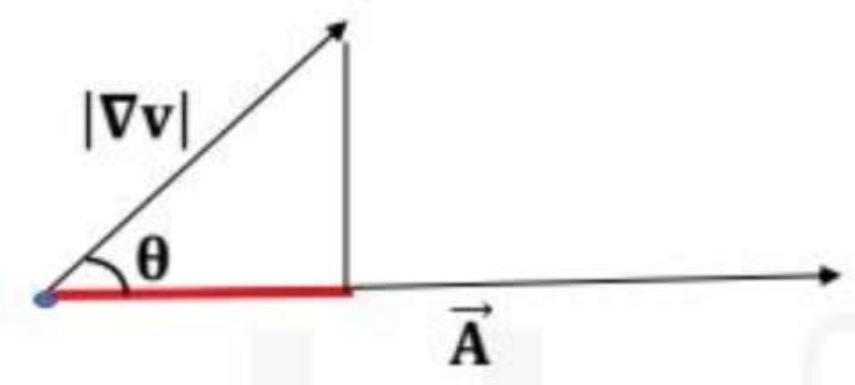


$$\nabla V = \vec{A}_1 + \vec{A}_2$$



# DIRECTIONAL DERIVATIVE

Application of gradient

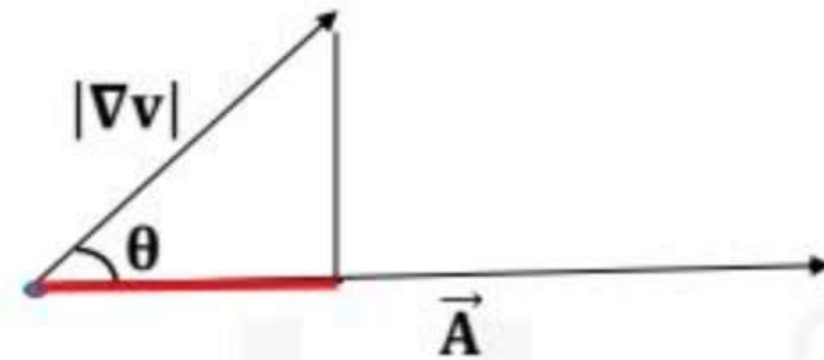


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## DIRECTIONAL DERIVATIVE

Application of gradient

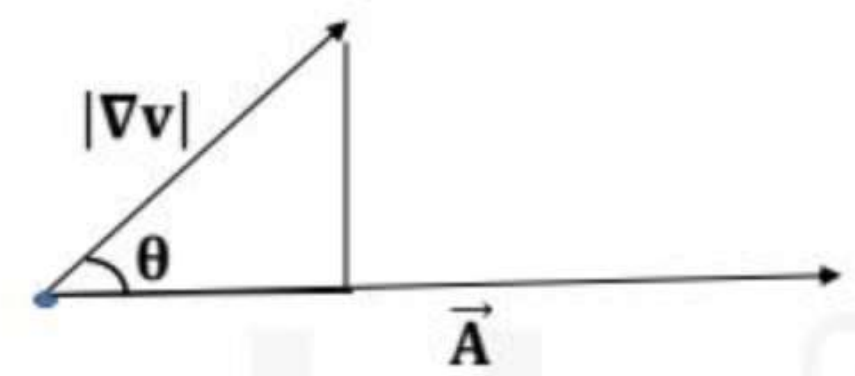


$|\nabla v| \cos\theta$



# DIRECTIONAL DERIVATIVE

Application of gradient



$|\nabla v| \cos\theta$

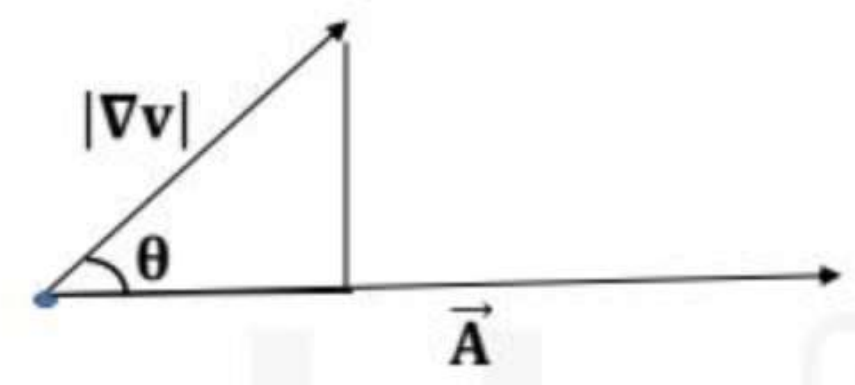


$\vec{A} \cdot \vec{B} = AB \cos\theta$



# DIRECTIONAL DERIVATIVE

Application of gradient



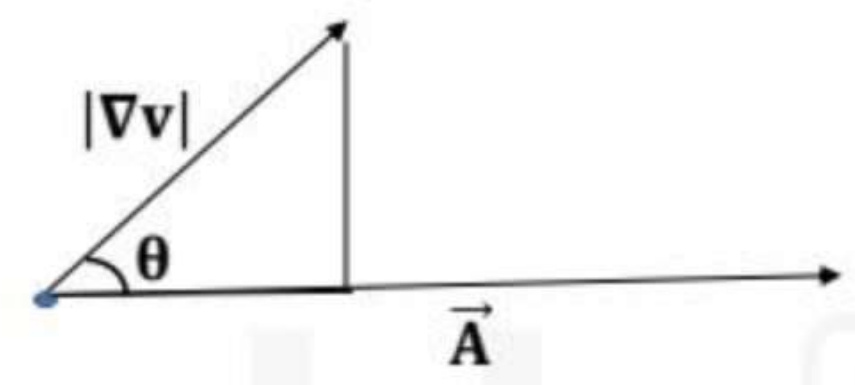
$$|\nabla v| \cos\theta$$

$$\vec{A} \cdot \vec{B} = AB \cos\theta$$

$$\vec{A} \cdot \hat{a}_B = A \cos\theta$$

# DIRECTIONAL DERIVATIVE

Application of gradient



$$|\nabla v| \cos \theta$$

$$\vec{\nabla v} \cdot \hat{a}_A$$

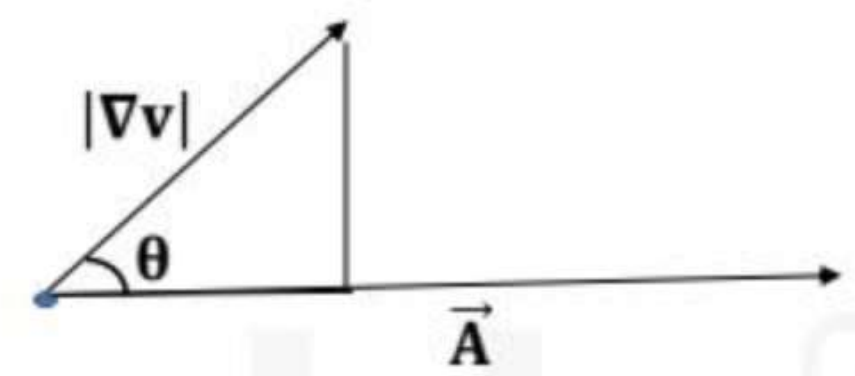
$$\vec{A} \cdot \vec{B} = AB \cos \theta$$

$$\vec{A} \cdot \hat{a}_B = A \cos \theta$$



# DIRECTIONAL DERIVATIVE

Application of gradient



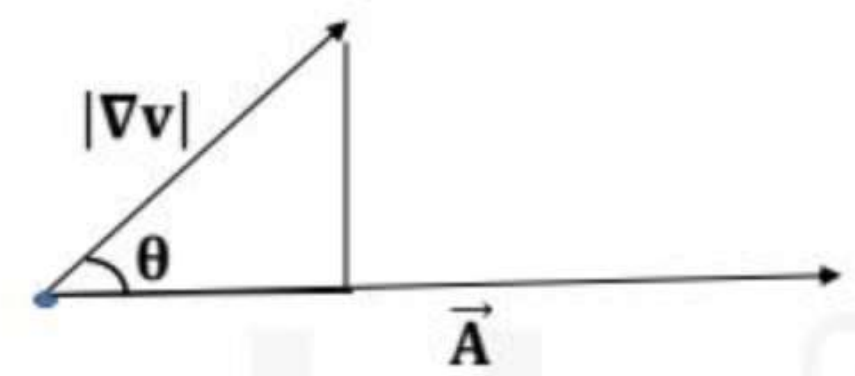
$$|\nabla v| \cos \theta$$
$$\vec{\nabla} v \cdot \hat{a}_A$$

$$\vec{A} \cdot \vec{B} = AB \cos \theta$$
$$\vec{A} \cdot \hat{a}_B = A \cos \theta$$

**Directional derivative of scalar  $v$  at a point in the direction of  $\vec{A}$**

## DIRECTIONAL DERIVATIVE

Application of gradient



$$|\nabla v| \cos\theta$$

$$\vec{\nabla}v \cdot \hat{a}_A$$

$$\vec{A} \cdot \vec{B} = AB \cos\theta$$

$$\vec{A} \cdot \hat{a}_B = A \cos\theta$$

Directional derivative of scalar  $v$  at a point in the direction of  $\vec{A} = \vec{\nabla}v \cdot \hat{a}_A$



**Find directional derivative of  $2x^2 + 3y - z$  in the direction of  $\vec{A} =$**

Q:24

**$5x\hat{i} - 2xz\hat{i} + 4\hat{k}$  at point  $(3, 1, -1)$**

Sol:

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**Find directional derivative of  $2x^2 + 3y - z$  in the direction of  $\vec{A} =$**

**$5x\hat{i} - 2xz\hat{i} + 4\hat{k}$  at point  $(3, 1, -1)$**

**Sol.**

**let  $V = 2x^2 + 3y - z$**

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**Find directional derivative of  $2x^2 + 3y - z$  in the direction of  $\vec{A} =$**

**$5x\hat{i} - 2xz\hat{i} + 4\hat{k}$  at point  $(3, 1, -1)$**

Sol.

let  $V = 2x^2 + 3y - z$

$$\nabla V = 4xi + 3\hat{i} - \hat{k}$$

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**Find directional derivative of  $2x^2 + 3y - z$  in the direction of  $\vec{A} = 5x\hat{i} - 2xz\hat{i} + 4\hat{k}$  at point  $(3, 1, -1)$**

Sol.

$$\text{let } V = 2x^2 + 3y - z$$

$$\nabla V = 4xi + 3\hat{i} - \hat{k}$$

$$\nabla V|_{(3,1,-1)} = 12\hat{i} + 3\hat{i} - \hat{k}$$



**Find directional derivative of  $2x^2 + 3y - z$  in the direction of  $\vec{A} =$**

**$5x\hat{i} - 2xz\hat{i} + 4\hat{k}$  at point  $(3, 1, -1)$**

Sol.

let  $V = 2x^2 + 3y - z$

$\nabla V = 4xi + 3\hat{i} - \hat{k}$

$\nabla_V|_{(3,1,-1)} = 12\hat{i} + 3\hat{i} - \hat{k}$

$\vec{A}|_{(3,1,-1)} = 15\hat{i} + 6\hat{i} + 4\hat{k}$

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$$\hat{a}_A = \frac{15\hat{i}+6\hat{i}+4\hat{k}}{\sqrt{225+36+16}}$$



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$$\text{Directional derivative} = \vec{\nabla}v \cdot \hat{a}_A$$

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$$\hat{a}_A = \frac{15\hat{i} + 6\hat{i} + 4\hat{k}}{\sqrt{225 + 36 + 16}}$$

$$\text{Directional derivative} = \vec{\nabla} V \cdot \hat{a}_A$$

$$\vec{\nabla} V \cdot \hat{a}_A = \frac{15 \times 12 + 6 \times 3 - 4}{\sqrt{277}}$$

**Q:24**

Find directional derivative of  $2x^2 + 3y - z$  in the direction of  $\vec{A} = 5x\hat{i} - 2xz\hat{i} + 4\hat{k}$  at point  $(3, 1, -1)$

Sol.

$$\text{let } V = 2x^2 + 3y - z$$

$$\nabla V = 4x\hat{i} + 3\hat{j} - \hat{k}$$

$$\nabla V|_{(3,1,-1)} = 12\hat{i} + 3\hat{j} - \hat{k}$$

$$\vec{A}|_{(3,1,-1)} = 15\hat{i} + 6\hat{j} + 4\hat{k}$$

$$\hat{a}_A = \frac{15\hat{i} + 6\hat{j} + 4\hat{k}}{\sqrt{225 + 36 + 16}}$$

$$\text{Directional derivative} = \vec{\nabla}V \cdot \hat{a}_A$$

$$\vec{\nabla}V \cdot \hat{a}_A = \frac{15 \times 12 + 6 \times 3 - 4}{\sqrt{277}}$$

$$= 11.656$$



Q:25

The directional derivative of  $f(x, y, z) = x(x^2 - y^2) - z$  at  $A(1, -1, 0)$  in the direction of  $\vec{p} = (2\hat{i} - 3\hat{j} + 6\hat{k})$  is:

$$\nabla f = (3x^2 - y^2)\hat{i} - 2xy\hat{j} - \hat{k}$$

1.  $-8/49$

$$\nabla f \Big|_{(1, -1, 0)} = 2\hat{i} + 2\hat{j} - \hat{k}$$

2.  $8/7$

$$\vec{p} \Big|_{(1, -1, 0)} = 2\hat{i} - 3\hat{j} + 6\hat{k}$$

✓ 3.  $-8/7$

$$\hat{q}_p = \frac{2\hat{i} - 3\hat{j} + 6\hat{k}}{\sqrt{4+9+36}}$$

4. 0

$$\text{directional der.} = \nabla f \cdot \hat{q}_p = \frac{4 - 6 - 6}{\sqrt{49}} = -\frac{8}{7}$$

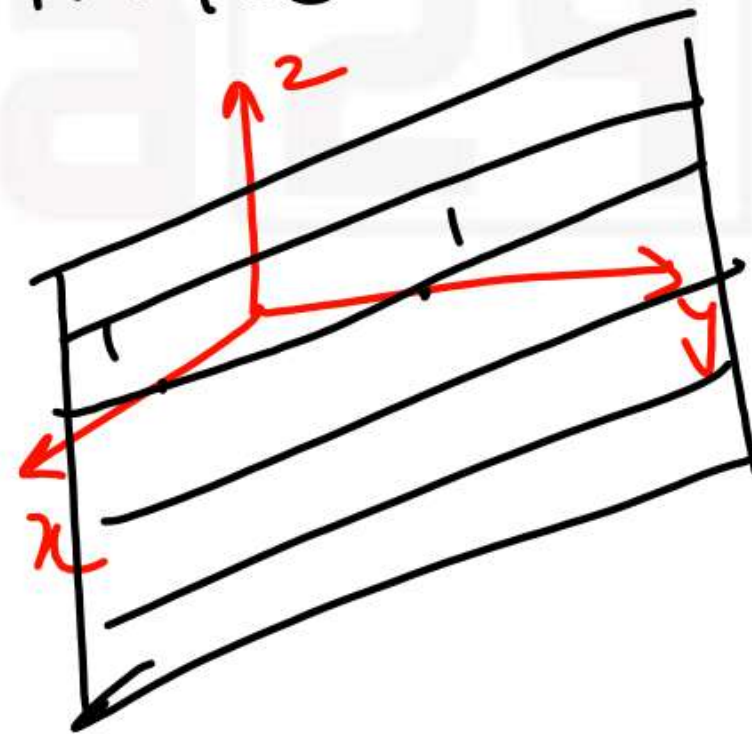
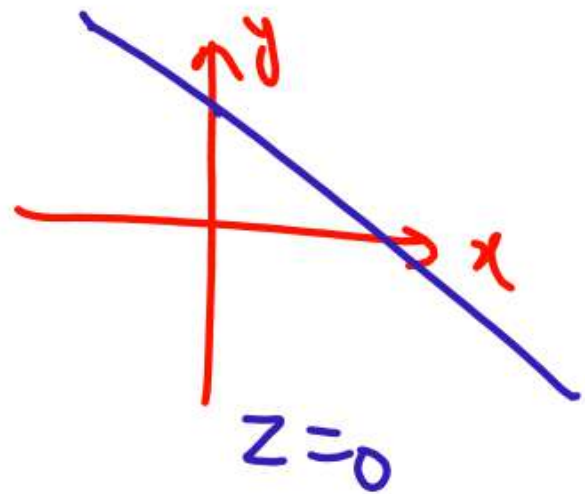


## Vector Normal to a Surface/Curve

$y = mx + c \rightarrow$  Curve which straight line

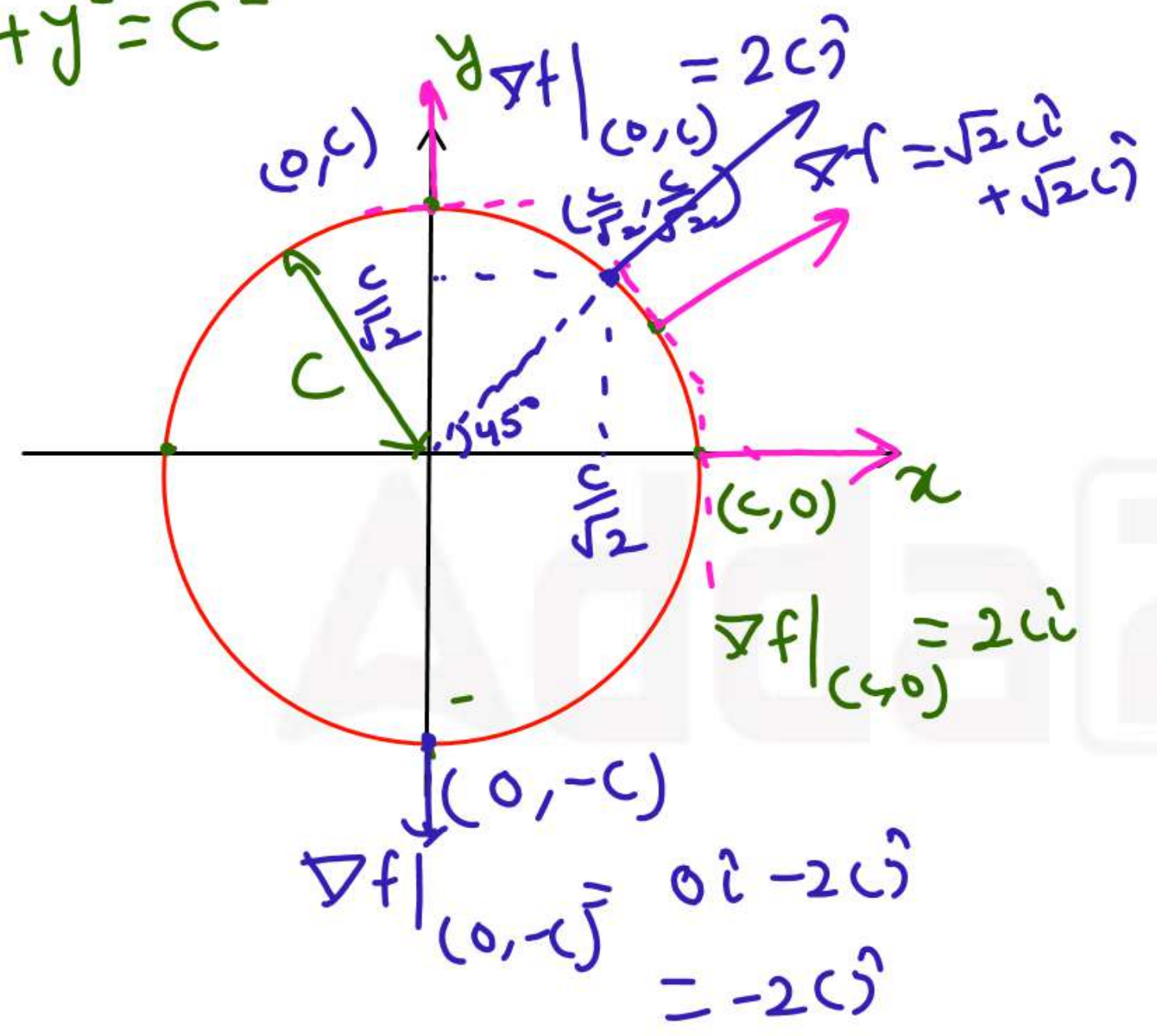
$x^2 + y^2 = c^2 \rightarrow$  Circular Curve

$x + y = 1 \quad \forall z \in (-\infty, \infty) \rightarrow$  Surface





$$x^2 + y^2 = c^2$$



$$x^2 + y^2 = c^2$$

$$x^2 + y^2 - c^2 = 0$$

$$f(x, y, z) = 0$$

$$\nabla f = 2x\hat{i} + 2y\hat{j} + 0\hat{k}$$



In general a curve or surface given by

$$f(x, y, z) = 0$$

$$f(\rho, \phi, z) = 0$$

$$f(r, \theta, \phi) = 0$$

then  $\nabla f$  at a point gives normal vector to that curve/surface at that point.

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# GATE 2024



Sat & Sunday

3 P.M.

## प्रचण्ड

Batch

6 PM → PSA → EE  
th, fri, Sat

9 P.M. EMFT

Engineering Mathematics

Mon, tu, wed → Comm

9 P.M

6 P.M

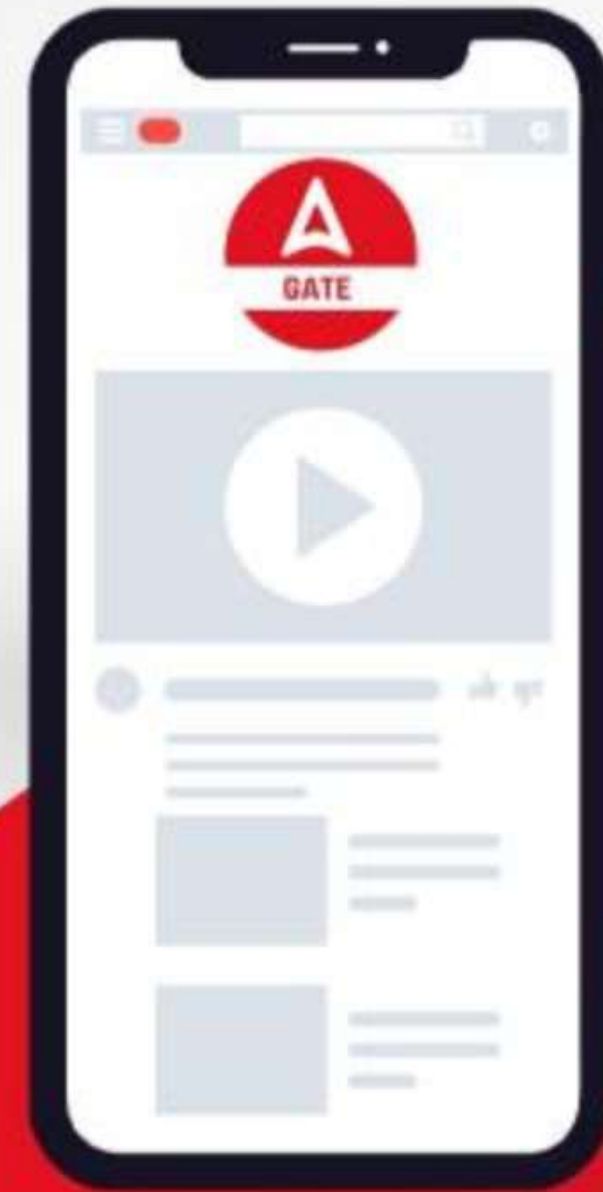
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✓ **LINEAR ALGEBRA**

**Question practice on basics of matrices**







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